Dear Editor,

Thank you for giving us the opportunity to submit the revised draft of our manuscript titled "Global PM_{2.5} prediction and associated mortality to 2100 under different climate change scenarios" to *Environmental Science & Technology*. We thank the insightful comments from the reviewers. Most of the suggestions made by reviewers have been incorporated and the changes made within the manuscript have been highlighted. Please see below, in blue, for a point-by-point response to the reviewers' comments and concerns. The page numbers and line numbers refer to the revised manuscript file with tracked changes.

Reviewers' comments:

Reviewer: 1

Comments:

The authors conducted a comprehensive study on evaluating the impact of ambient fine particulate matter (i.e., $PM_{2.5}$) concentrations on public health or premature mortality burden by the end of the 21st century under different climate change scenarios. This is an interdisciplinary research, representing a great concern to research communities, general public, and policy makers.

Through this study, the authors developed a deep machine learning model and applied it to project the future ambient $PM_{2.5}$ concentrations at a high resolution ($0.1^{\circ} \times 0.1^{\circ}$) on a global scale. With such a dataset, the authors completed a rigorous assessment of the impact of climate change-constrained air quality on human health. The results have important implications for policymakers to formulate feasible shared socioeconomic pathways to support sustainable development. Overall, the study is carefully-designed, the manuscript is well written and organized. However, several aspects need to be clarified before it is accepted to publish in EST.

<u>Author's Response:</u> We thank the constructive comments and suggestions from the reviewer. Based on your review comments, we have added more descriptions of the methodology and analysis of the results into the manuscript. The point-to-point responses are provided as follows.

Specific comments

<u>1. Reviewer #1 comment:</u> Details about the emission: Emissions inputs are critical for generating accurate $PM_{2.5}$ forecasts or projections. However, it is not clear what global emission inventories were used in the projection or predictions of $PM_{2.5}$ concentrations from 2021 to 2100. As indicated on Line 91, PKU-FUEL could be one of them. Are there any other global emission inventories included in the study? In addition, it will be helpful if some additional detailed information about the global emission

inventories used in this study can be provided. For instance, what are the base year(s) of emission inventories and what is the spatial resolution of original emission inventories?

Author's response: Thanks for your suggestion. We have added more detailed information about the global emission inventories used in this study in the revised manuscript (Lines 104–109).

"CMIP6 dataset contains historical emissions (1750 to 2014) and future emission data for SSP scenarios (2015-2100). CMIP6 emissions data were utilized in both the training and prediction processes. CMIP6 historical emissions data (1998–2014, the historical emissions data are available till 2014) were used to build the deep learning model, and the emission data of SSP scenarios for 2015 to 2019 were used in the deep learning model verification process. Future emission data for 2021–2100 were input into the trained deep learning model for prediction. The detailed narratives of emission inventory used in this study are summarized in Table S3."

Role in this	Emission inventory	Time	Original	Data citation	
study	in this study	period	Resolution		
Training	Historical emissions	1998-2014	0.5 ° x 0.5 °	Feng, et al. $(2020)^1$	
Verification	Emissions for SSP	2015 2010	0.5.0 - 0.5.0	Equal of $a1 (2020)$	
	scenarios	2013-2019	0.3×0.3	Feng, et al. (2020)	
Prediction	Emissions for SSP	2021 2100	050-050	Equal of $a1 (2020)$	
	scenarios	2021-2100	0.3×0.3	relig, et al. (2020)	

Table S3. Narratives of CMIP6 emission inventory used in this study.

<u>2. Reviewer #1 comment:</u> L88: Here the word "Primary" is a little bit confused since I assume the emissions of all $PM_{2.5}$ compositions are primary. When you use five pollutants as emission inputs to drive the deep learning model, what are the percentages of individual species?

Author's response: Thanks for your comment. We agreed with the reviewer, the word "primary" can be misleading. We have revised the below sentence in Lines 89-92: "Since the deficiency in the emissions of primary $PM_{2.5}$ components (except organic carbon (BC) and black carbon (OC)) in the CMIP6 datasets, future $PM_{2.5}$ concentrations are driven by changes to precursor emissions (ammonia (NH₃), nitrogen oxides (NOx), and sulfur dioxide (SO₂)), BC, OC and climate in this study."

Global emission amounts and percentages of the five species have been included in the supplementary information (SI), as shown in Table S1 and Table S2.

Species	1995	2000	2005	2010	2014	Unit
BC	8.12	7.46	8.84	9.66	9.74	Mt BC/yr
NOx	135.17	135.53	149.85	155.42	155.64	Mt NOx/yr
NH ₃	54.03	54.51	58.88	62.45	65.04	Mt NH ₃ /yr
OC	32.08	27.98	32.72	34.61	36.15	Mt OC/yr
SO_2	121.40	111.15	124.98	116.32	105.00	Mt SO ₂ /yr

Table S1. Global emission amount of BC, NOx, NH₃, OC and SO₂.

Table S2. Percentage (%) of historical BC, NOx, NH₃, OC and SO₂ emissions.

Species	1995	2000	2005	2010	2014
BC	2.3%	2.2%	2.4%	2.6%	2.6%
NOx	38.5%	40.3%	39.9%	41.1%	41.9%
NH ₃	15.4%	16.2%	15.7%	16.5%	17.5%
OC	9.1%	8.3%	8.7%	9.1%	9.7%
SO ₂	34.6%	33.0%	33.3%	30.7%	28.3%

<u>3. Reviewer #1 comment:</u> L117-118: There is a gap between historical simulations (1981-2010) and future projections (2021-2100). I'm curious as to the reasons for this.

Authors' response: Thank you for the comment. The classical period of climate, defined as the mean and variability of relevant quantities of certain variables over a period of time, is 30 years, which was recommended by the World Meteorological Organization (WMO).² WMO used a 30-year baseline for weather and climate, operating on the principle that 30 years of data provide enough information to even short-term variability and afford a reliable reference period for monitoring the general patterns of weather and climate. A widely used standard reference period for calculating climate normals is the 30-year period of 1981-2010.³ In order to keep the same number of years (30-year average) as 1981-2010, we followed the previous downscaling study ⁴ and set the future scenarios as four 30-year periods for climate downscaling. The future periods are set as 2021–2050 (2030s), 2041–2070 (2050s), 2061–2090 (2070s), and 2071–2100 (2080s), respectively.

<u>4. Reviewer #1 comment:</u> As pointed out on L119-122, four SSP scenarios were classified by socioeconomic, land use, and environmental development assumptions. Can you add a table to summarize the key differences among them in the Supplementary even though they were described in other references?

Authors' response: Thank you for your suggestion. We have further added a summarized table of key differences among four SSP scenarios in Table S5 in the supplemental material.

Table S5. Descriptions of the critical elements for SSP1-2.6, SSP2-4.5, SSP3-7.0, and SSP5-8.5relevant to air pollution

Scenario	Description	Land-use Change Regulation	Environmental Development	Pollution Control Policy	Energy Tech Change	Population Growth
SSP1-2.6	Sustainability	Strong regulation to avoid environmental tradeoffs	High environmental awareness; more inclusive development that respects perceived environmental boundaries	Strong	Directed away from fossil fuels, toward efficiency and renewables	Relatively Low
SSP2-4.5	Middle-of-the- road	Medium regulation; slow decline in the rate of deforestation	Medium environmental awareness; work toward but make slow progress in achieving sustainable development goals	Medium	Some investment in renewables but continued reliance on fossil fuels	Medium
SSP3-7.0	Regional rivalry	Limited regulation; continued deforestation	Low environmental awareness; strong environmental degradation in some regions	Weak	Slow tech change, directed toward domestic energy sources	High in developing countries; low in industrialized countries
SSP5-8.5	Fossil-fueled development	Medium regulation; slow decline in the rate of deforestation	High environmental awareness; local environmental problems are successfully managed	Strong	Directed toward fossil fuels; alternative sources not actively pursued	Relatively Low

<u>5. Reviewer #1 comment:</u> L122: Why do the authors highlight "radiative forcing" as an indicator to distinguish these four scenarios here? Is there any indication of "radiative forcing" to ambient levels of PM_{2.5} in the future or to the shared socioeconomic pathways?

Authors' response: Thank you for your question. The term "radiative forcing" has been employed in the IPCC Assessments to denote an externally imposed perturbation in the radiative energy budget of the Earth's climate system. Conceptually, "radiative forcing" is the change in energy flux caused by both natural and anthropogenic factors that affect the global energy balance and force changes in the Earth's climate.⁵ Changes in greenhouse gas concentrations in the atmosphere affect radiative forcing;

thus, radiative forcing corresponds to different greenhouse gas (GHG) emissions and the resulting climate change. The SSP scenarios translate the socioeconomic factors and mitigation goals into GHG emissions (and associated radiative forcing) in a standardized manner, indicating the social pathways associated with different levels of warming. For example, SSP 1-2.6, SSP2-4.5, SSP3-7.0, and SSP5-8.5 correspond to the low, medium, high, and very high GHG emissions scenarios, resulting in subsequent radiative forcing of 2.6, 4.5, 7.0, 8.5 Watt/m² by 2100. Hence, the IPCC report and previous literature used "radiative forcing values" to represent four different future pathways. Under different future "radiative forcing" conditions, emissions and meteorological conditions are different and such variations can be further propagated to the PM_{2.5} concentration. Previous studies have investigated the relationship between "radiative forcing" and the subsequent influence on ambient levels of PM_{2.5}. Colette et al. (2013)⁶ estimated that, due to the air pollutant emission reduction, the decrease in PM_{2.5} concentrations by 2050 in western Europe could reach up to 60% under radiative forcing of 8.5 Watt/m² and 75% under radiative forcing of 2.6 Watt/m².

To explain the "radiative forcing" as an indicator to climate change and its relationship with $PM_{2.5}$ concentration, we have added the following description from Line 148 to Line 158.

"Changes in greenhouse gas concentrations in the atmosphere affect radiative forcing; thus, 'radiative forcing' mentioned in this work corresponds to different greenhouse gas (GHG) emission scenarios and the resulting climate change. Both SSP1-2.6 and SSP5-8.5 represent strong climate mitigation scenarios,^{7, 8} with the distinction that the anthropogenic radiative forcings by 2100 are 2.6 Watt/m² and 8.5 Watt/m², respectively. ^{9, 10} SSP2-4.5 represents a moderate mitigation scenario and the radiative forcing is stabilized at 4.5 Watt/m² until 2100 by implementing moderately restrictive emission reduction measures and strategies.¹¹ SSP3-7.0 is the weakest climate mitigation scenario with an anthropogenic radiative forcing of 7.0 Watt/m² by 2100.¹²"

<u>6. Reviewer #1 comment:</u> Some details about the 80 years of global $PM_{2.5}$ projection (why not use prediction?): It requires significant computer resources to complete long-term global high-resolution (0.1°×0.1°) $PM_{2.5}$ predictions by using a 3D numerical climate-chemistry or air quality model. How much computer resources does the deep learning model need to complete the 80 years of simulations in this study?

Authors' response: Thanks for your comment. "Prediction" and "projection" are used to describe two different kinds of information that both significantly represent estimations about future conditions. "Prediction" is a probabilistic statement, i.e., a predictive relationship based on modeling some phenomenon from available data. In other words, "prediction" describes the forecasted climate for the coming months or years, which are strongly influenced by natural cycles of variability. While "projection" is a probabilistic statement that indicates about what happens in the future is possible if

certain conditions develop. Projection relies on prescribed scenario information which illuminates how scenarios of gas emissions and associated socioeconomic pathways will influence climate and air quality in the long term. In summary, the critical difference between "prediction" and "projection" is that projections generally rely on scenarios or assumptions regarding the future.

Regarding the computation resources cost, detailed information has been added to Text S2 in the SI (Page 4).

"In this study, all experiments were performed on a high-performance computing server with an Intel i7-10700 CPU and an NVIDIA Quadro RTX 4000 GPU. It takes about 20 seconds to execute each training epoch, and the total training time is about 5 hours. For the projection, it takes only 10 seconds on average to simulate every decade."

<u>7. Reviewer #1 comment:</u> As shown in Fig. 2, S2-4, the CNN model predictions show very good agreement with satellite-retrieved data. I know this is beyond of this study scope, but I am still interested in whether this model can be used to generating regional operational $PM_{2.5}$ forecasts. Any comments on that?

Authors' response: Thank you for your comment. Yes, the CNN model can also be used to predict regional PM_{2.5} concentration. PM_{2.5} is a cross-boundary pollution issue; thus, it is influenced not only by local but also by regional situations (e.g., meteorological conditions and emission intensities). At the same time, CNN is adept at obtaining spatial information and considering the regional influence, due to the fact that this type of deep learning model typically consists of a series of convolutional layers, pooling layers, and fully-connected layers.^{13, 14}

The CNN technique was found to have good performance in estimating the regional $PM_{2.5}$ concentration. A recent study developed a CNN model and used it for regional air quality forecast in South Korea.¹⁵ Results show that the R² values of PM_{2.5} and PM₁₀ predictions reached 0.975 and 0.976 respectively. For another PM_{2.5} forecast research in Beijing, China, results revealed that CNN has a more stable improvement in regional PM_{2.5} concentration prediction for the future 24 hours.¹⁶ Therefore, the CNN approach has the potential to perform reliable regional PM_{2.5} forecast.

<u>8. Reviewer #1 comment:</u> L152: Even though some explanations are provided here. I am still not very clear the reason(s) of implementing 8-fold cross-validation and the way of calculation. Are there any references on this?

Authors' response: Thanks for your comment. We agree with the reviewer that more descriptions and references are required to clarify the 8-fold cross-validation.

The core idea of cross-validation lies in dividing the dataset into several groups and averaging the results of multiple evaluations, thus thoroughly evaluating the proposed model and fully implementing all data for validation.^{17, 18} With cross-validation, all data can have the opportunity to become both training and validation datasets. Therefore, cross-validation can better evaluate the generalization ability and model performance.

We have added the calculation of 8-fold cross-validation in Text S7 in the SI (Page 7).

"Cross-validation is a resampling process used to evaluate machine/deep learning models on a limited sample of data,^{19,20} which has also been widely used in the verification of machine learning models for air pollution prediction.^{21,22} The core idea of cross-validation lies in dividing the dataset into several groups and averaging the results of multiple evaluations, thus thoroughly evaluating the proposed model and fully implementing all data for validation.¹⁷

The procedure of 8-fold cross-validation is as follows.

- 1. Full set of the input data is divided into 8 parts.
- 2. In the training process, each time, one part of the input data is withheld, and the remaining 7 parts are input to the CNN framework to train the model.
- *3. The correlation coefficient (CORR_i) and RMSEi are calculated by validation with the withheld one-part data.*
- 4. Steps 2 and 3 are performed 8 times, and then 8 times of RMSE_i and CORR_i can be calculated.
- 5. The final RMSE and CORR are calculated by averaging the 8 different RMSE_i and CORR_i."

<u>9. Reviewer #1 comment:</u> $PM_{2.5}$ exposure concentrations are widely used in health impact studies while ambient levels of $PM_{2.5}$ are more commonly used in air quality or atmospheric environment studies. Is(are) there any difference(s) between both in terms of values?

Authors' response: Thanks for your comment. Yes, there exist differences between the PM_{2.5} exposure concentrations and ambient levels in terms of values.

The "exposure concentration" can be used to indicate the people's actual exposure to environmental $PM_{2.5}$ concentrations.²³ In real life, due to the influence of the natural environment and urban layout, residents usually gather in the city center, and the urban population is unevenly distributed. Directly using the ambient $PM_{2.5}$ concentration to assess the population exposure, without considering the disproportionate spatial-temporal distributions of the pollution and the population, might not reflect the true impact of air pollution on health. The criticism that "the ambient levels of $PM_{2.5}$ may not properly reflect individual exposures" has been supported by studies since the 1980s. A series of

studies have found that personal exposures to particulate matter were much higher than the average ambient concentrations.²⁴⁻²⁶

To clarify, we have added the description and calculation results of "exposure" in Text S5 in the SI (Page 6).

"Population-weighted concentration can better reflect the impact of $PM_{2.5}$ pollution on the exposed population, and thus build a more reliable theoretical basis for public health assessment. Eq. (S5) and Eq. (S6) were used to calculate the exposure concentration ($C_{PM_{2.5}}^{i-pop}$) and spatial ambient levels ($C_{PM_{2.5}}^{i-space}$) of $PM_{2.5}$, respectively.

$$C_{PM_{2.5}}^{i-pop} = \left(\sum_{k=1}^{N} C_k^i * P_k^i\right) / \sum_{k=1}^{N} P_k^i \qquad Eq. (S5)$$
$$C_{PM_{2.5}}^{i-space} = \frac{1}{N} \left(\sum_{k=1}^{N} C_k^i\right) \qquad Eq. (S6)$$

Here, different countries and the total grid number of the country are represented by i and N, respectively. C_k^i and P_k^i are the $PM_{2.5}$ concentration and corresponding population of grid k in country i, respectively."

A clear difference between the exposure and spatial ambient level can be found in Table A1, with exposure at the national level being generally higher in values than the corresponding spatial ambient level of $PM_{2.5}$.

Country	Exposure [μg/m ³]	Ambient level [µg/m³]	Population [in million]
Global	44	14	7366
Australia	6	1.5	24
Brazil	11	6.1	207
Canada	7	2.9	36
China	58	18.7	1383
France	12	8.7	65
India	72	39.4	1311
Japan	13	10.8	128
Philippines	23	4.6	100
Russia	17	6.7	148
Singapore	19	27.6	4

Table A1. Country-level population-weighted exposure and spatial-weighted PM2.5concentrations in 2015.

South Africa	30	13.1	53
South Korea	29	24.7	50
South Sudan	32	12.1	12
Spain	10	6.3	48
Turkey	36	12.9	78
United States	8	6.0	323
Vietnam	28	18.0	93

<u>10. Reviewer #1 comment:</u> L298-301: The impact of driving factors could be quite complex. The authors highlighted the importance of the planetary layer height for the SSP3-7.0 scenario in Figure. S7 and on lines 298-301. However, if you look closely at Figs. S5, S6, and S8, the delta changes of surface temperature, specific humidity, and sea level pressure are more significant than the change in PBLH for Scenarios SSP 3-7.0 and 5-8.5. Any comments on that?

Authors' response: Thank you very much for your comment. We agree with the reviewer that meteorological conditions affect the accumulation and diffusion of PM_{2.5} through multiple mechanisms. Influence of PBLH on PM_{2.5} concentrations has been reported in several previous studies. PM_{2.5} concentrations are highly sensitive to PBLH, which decides the vertical space to which PM_{2.5} can disperse.²⁷ With a given amount of emitted pollutants, lower PBL height can generally cause the pollution episode of PM_{2.5}.^{28, 29} That's the main reason why we want to emphasize the role of PBLH on PM_{2.5} concentration in the manuscript. Although the differences in pressure, temperature, and specific humidity are also significant as pointed out by the reviewer, their impacts on PM_{2.5} pollution are not linear and straightforward. Based on your comment, we have modified our description of the influence of meteorological factors (Lines 425–436).

"Under the SSP3-7.0 scenario, the planetary boundary layer height (PBLH) exerts strong influence on $PM_{2.5}$ dispersion, and thus its decreases in East Asia, South Asia, and eastern Africa (Figure S10) will increase the $PM_{2.5}$ concentrations. Besides PBLH, other meteorological conditions, such as higher temperature,³⁰ are also favorable for $PM_{2.5}$ accumulation in these regions and therefore exacerbate the $PM_{2.5}$ -associated mortality burden until the 2050s." <u>11. Reviewer #1 comment:</u> Differences in key meteorological fields (e.g., PBLH, surface temperature, etc.) are presented in Figures S5-S9. It will be helpful to include similar changes in emissions for four scenarios if they are different.

Authors' response: Thank you for your suggestion. We have added below figures to reveal the changes of emissions in the supplementary material. (SI Page 23-25)

"Emissions (SO₂, NH₃, OC, BC, NOx) for the four SSP scenarios up to 2100 are shown in Figures S13-S17."



Figure S13. Changes in SO₂ emission (g km⁻² yr⁻¹ in log scale) for 2030s (2021-2050 average), 2050s (2041-2070 average), 2070s (2061-2090 average), and 2080s (2071-2100 average) compared to that in 1990s (1981-2010) under the four scenarios.



Figure S14. Changes in NH₃ emission (g km⁻² yr⁻¹ in log scale) for 2030s (2021-2050 average), 2050s (2041-2070 average), 2070s (2061-2090 average), and 2080s (2071-2100 average) compared to that in 1990s (1981-2010) under the four scenarios.



Figure S15. Changes in OC emission (g km⁻² yr⁻¹ in log scale) for 2030s (2021-2050 average), 2050s (2041-2070 average), 2070s (2061-2090 average), and 2080s (2071-2100 average) compared to that in 1990s (1981-2010) under the four scenarios.



Figure S16. Changes in BC emission (g km⁻² yr⁻¹ in log scale) for 2030s (2021-2050 average), 2050s (2041-2070 average), 2070s (2061-2090 average), and 2080s (2071-2100 average) compared to that in 1990s (1981-2010) under the four scenarios.



Figure S17. Changes in NOx emission (g km⁻² yr⁻¹ in log scale) for 2030s (2021-2050 average), 2050s (2041-2070 average), 2070s (2061-2090 average), and 2080s (2071-2100 average) compared to that in 1990s (1981-2010) under the four scenarios.

Minor comments:

1. Reviewer #1 comment: L25: Please spell out CI.

Authors' response: Thanks for your comment. We have spelled out the CI (Confidence Interval) in the manuscript (Line 377).

<u>2. Reviewer #1 comment:</u> L63: "and emissions" or "emissions"? Do you need a "and" before "emissions"?

Authors' response: We are sorry for the typo, and it has been corrected.

3. Reviewer #1 comment: L97: What are the "primary spatial resolutions"?

Authors' response: To avoid misunderstanding, we have revised the "primary spatial resolutions" to "original spatial resolutions". Also, we have added more information about the original spatial resolutions in the manuscript. (Line 113–115)

"Before training the deep learning model, all meteorological and emissions data were re-interpolated from their original spatial resolutions (meteorological data with $0.625^{\circ} \times 0.500^{\circ}$ and emission data with $0.5^{\circ} \times 0.5^{\circ}$) into the same grid as the surface PM_{2.5} data with a resolution of $0.1^{\circ} \times 0.1^{\circ}$."

<u>4. Reviewer #1 comment:</u> L152: please provide a little bit detail about the calculation of 8-fold cross-validation.

Authors' response: Thanks for your comment. We have added the description and calculations of 8-fold in Text S5 in the SI (Page 6).

"Cross-validation is a resampling process used to evaluate machine/deep learning models on a limited sample of data,^{19,20} which has also been widely used in the verification of machine learning models for air pollution prediction.^{21,22} The core idea of cross-validation lies in dividing the dataset into several groups and averaging the results of multiple evaluations, thus thoroughly evaluating the proposed model and fully implementing all data for validation.¹⁷

The procedure of 8-fold cross-validation is as follows.

- 1. Full set of the input data is divided into 8 parts.
- 2. In the training process, each time, one part of the input data is withheld, and the remaining 7 parts are input to the CNN framework to train the model.
- 3. The correlation coefficient (CORR_i) and RMSEi are calculated by validation with the withheld one-part data.
- 4. Steps 2 and 3 are performed 8 times, and then achieve 8 times of RMSE_i and CORR_i.
- 5. The final RMSE and CORR are calculated by averaging the 8 different RMSE_i and CORR_i."

5. Reviewer #1 comment: L176: Figure2: What are the time period and scope of the validation presented in the figure?

Authors' response: Thanks for your comment. We have included the time period and scope in the caption of Figure 2.

"Figure 2. 8-fold cross-validation of the global PM_{2.5} concentrations predicted by the U-Net CNN model during 1998-2014. The color represents the sample density."

<u>6. Reviewer #1 comment:</u> L195: Figure 3: Each panel subplot includes a letter label. It is necessary to include them in the figure caption.

Authors' response: Thank you for the suggestion. We have included a letter label for each panel subplot in this figure caption.



"Figure 3. Spatial distribution of changes in projected global $PM_{2.5}$ concentrations relative to the baseline period (2010–2019) under different climate change scenarios. Panels (a)-(d) represent the changes in $PM_{2.5}$ concentration for 2030s (2021-2050 average), 2050s (2041-2070 average), 2070s (2061-2090 average), and 2080s (2071-2100 average) under SSP1-2.6 scenarios compared to the baseline condition. Panels (e)-(h) represent that of the same period but under SSP2-4.5. Panels (i)-(l) represent that of the same period but under SSP3-7.0. Panels (m)-(p) represent that of the same period but under SSP5-8.5."

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Reviewer: 2

Comments:

The authors have developed a machine learning-based approach to predicting monthly average PM_{2.5} concentrations at high spatial resolution (0.1 degree), trained on MERRA2 reanalysis fields, historical emissions from CMIP6, and PM_{2.5} data based on satellite observations and GEOS-Chem simulations. This trained model is then applied to estimate monthly average PM_{2.5} concentrations from 28 CMIP6 global climate models for each month from 2015 to 2100, for each of four SSPs. The resulting PM_{2.5} concentrations are then used with future projections of population distributions to estimate PM_{2.5}-associated mortality. The subject is certainly of interest for ES&T. However, I cannot recommend this manuscript for publication in its current form.

<u>Authors' response:</u> We are grateful for the constructive comments. Substantial revisions have been made for the manuscript based on your comments. The U-Net model has been described and elaborated in more detail in the revised manuscript, accompanied by the replotting of the U-Net architecture with additional detailed information on model structure and parameters. More discussions of the model results, such as generalisation and standard error, have been added. In addition, the implications of the study have been further elaborated in the revised manuscript, with a focus on the economic impact of future premature mortality associated with PM_{2.5}. The point-by-point response to your questions are listed as follows. The page numbers and line numbers refer to the revised manuscript file with tracked changes.

<u>1. Reviewer #2 comment:</u> First, the most interesting and novel aspect of this analysis, and where the authors clearly have expertise, is the U-Net machine learning model. However, the description of this model is inadequate for me to follow, and I suspect inadequate for the majority of readers of this journal. The authors do provide many references, but in my opinion more details in this paper are warranted, at least in the Supplement. Figure 1 raises more questions for me than it answers, and the supplementary text S1 does not have much depth. Are w and s equal to 3600 and 1800 (representing 0.1 degrees longitude and latitude?). What value is used for the shuffle factor s? What is ADMM, and how does the learning rate enter into the equation S2? Did the authors use their own custom code, or

did they use existing machine learning packages? What is the reason for subtracting 2.4 ug/m^3 from the PM_{2.5} concentration (Text S3)? Why 64 channels? The SI includes this unhelpful fragment: "For more details about these parameters" without referring the reader to where those details may be obtained.

Authors' response: Thank you very much for the comments.

In this work, we aimed to predict $PM_{2.5}$ concentration based on meteorological and emission data, as shown in Eq. (S1):

$$x \xrightarrow{f:U-Net} y$$
 Eq. (S1)

where $\mathbf{X} = (X_1, ..., X_T)$ represents the meteorological and pollutant emissions data over *T* months, $\mathbf{y} = (Y_1, ..., Y_T)$ represents surface PM_{2.5} concentrations in the corresponding *T* months, and *f* is the well-trained U-net CNN model.

The U-net CNN model is used to learn the relationship between meteorological variables, emissions (\mathbf{X}) and PM_{2.5} concentration (\mathbf{Y}) . CNN model we used is an image-based multilayer feedforward neural network. In this work, the meteorological and emission fields (\mathbf{X}) and PM_{2.5} concentration fields (\mathbf{Y}) were treated as 2-D images. The geographic range of the meteorological fields, emissions, and global PM_{2.5} concentrations in this study is 180°W to 180°E, 69.75°N to 54.75°S, with a resolution of $0.1^{\circ} \times 0.1^{\circ}$. Therefore, the size of 2-D images is equal to 3600×1246 .

The architecture of U-net CNN consists of a contracting path to capture the context in images and a symmetric expansive path to expand the image size.¹ In the contracting path, convolutional layers and max-pooling layers are included. The convolutional layer, which can extract data features, is the key to CNN. The convolutional layer relies on convolutional nuclei to extract the features from the input (meteorological and emissions data) and the target (PM_{2.5} concentration), and to obtain a complete feature map of the input and target data by sliding the convolutional kernel.² The maxpooling layer is mainly used for feature dimensionality reduction and also for improving the quality of the extracted information.³ In the expansive path, up-sampling layers, convolutional layers, copy connection, and a final output layer are included. The up-sampling layer is designed to expand the image size so that the expanded features can be concatenated with feature maps from the corresponding

max-pooling layer. The convolutional layers in the expansive path are used to combine the information from the contracting path (including high-level features extracted from the original image) and the information from the copy connections (including detailed features copied from the contracting path). After the above-mentioned operations, the U-net CNN model can mine the deep features implied between PM_{2.5} concentration and meteorological and emissions data.

To clarify the architecture of the U-net model and explain the parameters in the supplementary information (SI), we replotted the model architecture and added more detailed descriptions of the U-net model in Text S2 (SI Page 2–3).

"In this study, the meteorological, emission fields, and PM_{2.5} concentration fields are treated as 2-D images. The detailed architecture of our proposed U-Net for PM_{2.5} projection is shown in Figure 1. There are mainly three parts in U-Net, i.e., contracting path, bottleneck, and expansive path. In the contracting path, the multichannel input images first went through two contraction blocks. Each contraction block, aimed to capture and aggregate the spatial features, is comprised of two convolution layers (represented as yellow cuboid) and one max-pooling layer (represented as orange cuboid). All the convolution layers share the same kernel size of 3×3 and utilize Rectified Linear Unit (ReLU) as the activation function. Max-pooling layers are adopted for adjusting the size of images in order to obtain better bottleneck information. After each block, the image size will be halved by using the max pooling layer with kernel size of 2×2 , but the number of channels will be doubled. In the bottleneck part, combined with two convolution layers, the most crucial spatial information was automatically extracted and refined with the smallest intermediate images, which is crucial to ensure the accuracy of the final prediction. In the expansive path, each block consists of one up-sampling *layers (represented as black cuboid) and three 3×3 convolution layers, and one copy connection layer* (represented as blue cuboid). The up-sampling layer (with kernel size 2×2) is designed to expand the image size so that the expanded features could be concatenated with feature maps from the corresponding contraction layer. The copy connection is to ensure that the detailed features learned by contraction can be directly used for reconstruction. The arrows with different colors in Figure 1 indicate the information flow in different parts of the model. At the end of the expansion part, a final layer with kernel size 1×1 helps make the final prediction of the estimated $PM_{2.5}$ concentration."



Figure 1. Architecture of the U-Net model

Are w and s equal to 3600 and 1800 (representing 0.1 degrees longitude and latitude?). What value is used for the shuffle factor s?

Authors' response: In this work, the meteorological and emission fields and $PM_{2.5}$ concentration fields are treated as 2-D images. Since the initial data of $PM_{2.5}$ surface concentrations are not available in the Arctic and Antarctic Circle, the geographic range of global $PM_{2.5}$ concentrations predicted in this study is 180°W to 180°E, 69.75°N to 54.75°S, with a resolution of $0.1^{\circ} \times 0.1^{\circ}$. Therefore, w (width) and h (hight) are equal to 3600 and 1246, respectively.

Directly inputting data with a $0.1^{\circ} \times 0.1^{\circ}$ grid resolution would lead to a large computation load for deep learning. However, reducing the input size would cause inevitable information loss for the deep learning model, which would degrade the prediction performance. To overcome this barrier, the inverse pixel shuffle strategy was used to rearrange images to reduce the computational load without losing image information.

The steps of inverse pixel shuffle strategy are as follows. First, the original high-resolution images were separated into s² parts. Secondly, the inverse pixel shuffle rearranges the raw input with size $w \times h$ to form s² sample images with a size of $\frac{w}{s} \times \frac{h}{s}$. We set the s (shuffle factor) to 6, which means

that the original input (3600 * 1246) is divided into 6^2 samples with the size of 600×208 by inverse pixel shuffle.

We have revised the descriptions in Text S2 (SI Page 4).

"The inverse pixel shuffle strategy was used to reduce the computational load without information loss, as shown in Figure S1. In this way, the computational load was reduced, and the training data could be fully processed. For the inverse pixel shuffle operation with shuffle factor s, the raw input with size $w \times h$ was separated and reorganized into s^2 sample images with a size of $\frac{w}{s} \times \frac{h}{s}$, where w and h are equal to 3600 and 1246 (representing longitude 180°W to 180°E, latitude 69.75°N to 54.75°S with a resolution of 0.1° × 0.1°), and s set to 6. "

What is ADMM, and how does the learning rate enter into the equation S2?

Authors' response: Thanks for your comments. We have clarified the ADMM and learning rate in Text S2 (SI Page 3–4).

"Alternating Direction Method of Multipliers (ADMM) algorithm is a widely used optimization method for the constrained problems in machine learning technique. The principle and detailed information of ADMM can be found in Boyd, et al. (2011)⁴ From the perspective of solving constrained problems, this method is generated mainly to compensate for the disadvantages of quadratic penalties. In some problems, approximating constrained problems with quadratic penalties near the optimal point requires the coefficients of the penalty terms to converge to infinity, which will make the Heisenberg matrix very large, so the approximate objective function is very unstable. To solve this limitation, a linear approximation is introduced, in which the coefficients of the linear terms continuously approach the optimal solution (pairwise ascent), so that the solution can be obtained with the required accuracy even if the coefficients of the quadratic penalty terms are small. Moreover, from the perspective of solving distributed problems, ADMM decomposes the large global problem into several smaller and easier-to-solve local subproblems through the Decomposition-Coordination process. Boyd, et al. (2011)⁴ have proved its applicability to large-scale distributed optimization problems. Since ADMM is a mature and popular general framework for constraint optimization, we used the ADMM as the optimizer in this study.

The learning rate (0.001 in this study) is a tunable parameter in an optimization algorithm that determines the step size at each iteration while moving toward a minimum loss function (Eq. S2). The learning rate is usually determined from the gradient of the loss function."

$$\min_{\mathbf{f}} \sum_{t=1}^{T} \left(\mathbf{Y}_{t} - f(\mathbf{X}_{t}) \right)^{2} \qquad \qquad Eq. \ (S2)$$

Did the authors use their own custom code, or did they use existing machine learning packages? Authors' response: The U-net CNN model was built by using our own custom code in this study.

What is the reason for subtracting 2.4 ug/m³ from the PM_{2.5} concentration (Text S3)?

Authors' response: According to the GEMM model⁵, 2.4 μ g/m³ represents the counterfactual PM_{2.5} concentration. If the PM_{2.5} concentration is lower than 2.4 μ g/m³, no adverse health impact is assumed. In other word, the health impact of PM_{2.5} are only estimated above the counterfactual concentration, therefore the PM_{2.5} concentration should be subtracted by 2.4 μ g/m³.

To explain the reason for subtracting 2.4 μ g/m³, we added more information in Text S6 (SI Page 7).

"where $z = max (0, PM_{2.5} - 2.4 \ \mu g/m^3)$, 2.4 $\mu g/m^3$ represents the counterfactual $PM_{2.5}$ concentration. No adverse health impact is assumed when the $PM_{2.5}$ concentration is lower than this counterfactual concentration."

Why 64 channels?

Authors' response: 64 channel is a popular model setting and it is based on the trial and error from previous studies.⁶ In machine/deep learning research, it is customary to use the multiple of 2 as the channel number.

The SI includes this unhelpful fragment: "For more details about these parameters" without referring the reader to where those details may be obtained.

Authors' response: We are sorry for the typo and we have revised the sentence.

"For more details about these parameters, please refer to Burnett et al. (2018) 7"

2. Reviewer #2 comment: Second, more discussion is warranted as to the capabilities of the model. The average results shown (Fig S2) are impressive in terms of how well they match the satellite data, but what is the standard error of the monthly estimates? How does the variability seen in the training set compare to the future conditions, with changes in emissions and meteorology? Do any of the CMIP models include atmospheric chemistry components, which could be used as an independent check on the U-Net model results? What accounts for the anomalous increases in $PM_{2.5}$ in isolated regions of central Africa (Fig. 3)? Are wildfire emissions included in the historical CMIP emissions data? They almost certainly are not included in the future SSP emissions data. The same is true for windblown dust. What are the implications of these limitations for the analysis?

Authors' response: We very much appreciate the helpful comments and have added more discussions on the capabilities of the model.

The average results shown (Fig S2) are impressive in terms of how well they match the satellite data, but what is the standard error of the monthly estimates?

Authors' response: Thanks for your question, if we understand correctly, the reviewer means the standard error of performance for monthly estimates. We have added the Root Mean Squared Error (RMSE), which is related to the standard error of the mean, in Table 1. Table 1 represents the 8-fold cross-validation for the monthly mean, where the standard errors of the relevant metric are included. Values in the first row indicate the means of performance metrics (NMB, NME, MB, MAGE, RMSE, and R) on the monthly estimates, and the values in the second row indicate the standard error of statistics (NMB, NME, MB, MAGE, RMSE, and R) of the monthly estimates. The standard error of performance metrics was used to evaluate the variability of performance metrics on monthly estimates.

	NMB*	NME*	MB* (μg/m ³)	MAGE* (µg/m ³)	RMSE* (µg/m ³)	R
Average	-0.01	0.22	-0.05	1.36	4.02	0.987
Standard error	0.01	0.03	0.08	0.11	0.39	0.010

Table 1. 8-fold cross-validation of U-Net CNN model performance

*NMB: normalized mean bias; NME: normalized mean error; MB: mean bias; MAGE: mean absolute gross error;

RMSE: Root Mean Squared Error

How does the variability seen in the training set compare to the future conditions, with changes in emissions and meteorology?

Authors' response: To elucidate the changes in the inputs, we plotted the data distribution of the training dataset and inputs under the four SSPs with the data from 2071-2100 as an example. We have described the dataset distributions in Text S1 (SI Page 2).

Text S1. Frequency distribution of current and future data

Figure S1 and Figure S2 show the frequency distributions of current and future meteorological and emission data. For the meteorological inputs in Figure S1, overall, the distributions for current and future scenarios are similar. For example, the PBLH within the ranges of 350m to 1200m appears in high frequency under current and future scenarios. The temperature and specific humidity under current and future scenarios are skewed to the right and contain similar distribution patterns.

For emissions inputs, since the difference between the maximum (up to 8×10^6 g km⁻² yr⁻¹) and minimum (0 g km⁻² yr⁻¹) values is very large, in order to be able to compactly display numerical data with such a wide range of values, we used logarithmic scale here to present the distribution. In Figure S2, the change in OC emission is the most noticeable and the peaks in future scenarios tend to shift towards higher values. However, overall, few significant changes were found in the shape of the distribution (peaks, symmetry, skewness, uniformity) for either meteorology or emission input. Therefore, although the values between current periods and future scenarios differ, the distribution variations are subtle and the U-Net deep learning model applied in this work has the capability to digest the data of future scenarios.



Figure S1. Frequency distribution of meteorological inputs for the four SSPs in the 2080s (2071-2100) compared with the training dataset (1998-2014). The x-axis corresponds to the value of meteorological inputs, and the y-axis represents the frequency counts falling in each interval. Units for the x-axis of PBLH, temperature, specific humidity, wind speed, and sea level pressure are m, °C, kg/kg, m/s, and kPa, respectively.



Figure S2. Frequency distribution of emission (g km⁻² yr⁻¹ in log scale) for the four SSPs in the 2080s (2071-2100) compared with the training dataset (1998-2014). The x-axis corresponds to the value of emission inputs in the log scale, and the y-axis represents the frequency counts falling in each interval. Units for the x-axis are g km⁻² yr⁻¹ in log scale.

Do any of the CMIP models include atmospheric chemistry components, which could be used as an independent check on the U-Net model results?

Authors' response: Thanks for your comments. Some CMIP6 models do include atmospheric chemical components of PM_{2.5} (e.g., organic aerosol and sulfate), however, the dataset from some of models in CMIP6 platform do not contain PM_{2.5}. For those models that contain the PM_{2.5} data, the calculations

of PM_{2.5} are inconsistent due to the different treatments of aerosols and their components. For example, only Goddard Institute for Space Studies ModelE2.1 (GISS-E2-1-H) and Geophysical Fluid Dynamics Laboratory's Earth System Model Version 4 (GFDL-ESM4) have provided nitrate mass mixing ratios. Therefore, the CMIP6 dataset does not contain the complete set of aerosol component data, and the aerosol data from this dataset cannot be used as an independent check for the U-Net model results.

In some of previous studies,^{8,9} future $PM_{2.5}$ concentration projection was generally based on a simple equation. Surface $PM_{2.5}$ was estimated as the sum of the mass of individual species of black carbon (BC), OA, sulphate (SO₄), sea salt (SS) and dust (DU). All BC, OA and SO₄ aerosol masses were assumed to be presented in the fine-size fraction (< 2.5 µm), while a factor of 0.25 for SS and 0.1 for DU was used to calculate the approximate contribution of these components to the fine particulate matter (Eq. A1).

$$PM_{2.5} = BC + OA + SO_4 + NH_4 + (0.25 \times SS) + (0.1 \times dust)$$
 Eq. (A1)

A comprehensive study has systematically compared simulated $PM_{2.5}$ concentrations based on Eq. A1 with observed surface $PM_{2.5}$ concentrations (obtained from ground-based observations and reanalysis products).⁸ Compared to ground-based observations from the Global Aerosol Synthesis and Science Project database, the PM_{2.5} concentration estimated from Eq. A1 by inputting the component data from CMIP6 dataset was underestimated by up to 10 μ g m⁻³. ^{10, 11}

Therefore, the $PM_{2.5}$ concentrations estimated by this equation will differ numerically from the actual concentrations and from our U-Net results, so it is not reliable to use the output from CMIP6 for the direct verification.

What accounts for the anomalous increases in PM_{2.5} in isolated regions of central Africa (Fig. 3)?

Authors' response: Thank you for your comment. The increases in $PM_{2.5}$ in central Africa compared with the baseline values are mainly caused by the emission changes in these regions. To illustrate this issue more clearly, we have provided spatial emission maps for Africa. The anomalous increases in central Africa occurred in the SSP3-7.0 and SSP5-8.5 scenarios, so we compare emissions of SSP3-7.0 and SSP5-8.5 scenarios with those of the 1990s. As shown in Figure 3, $PM_{2.5}$ concentrations

continued to exceed baseline values in central Africa (e.g., The Republic of Niger, The Republic of Mali, The Republic of Chad, and The Republic of Sudan) under SSP3-7.0 scenario until the end of the 21st century. This area is quite consistent with the emission-increasing region, as shown in Figures S5 and S6, which means that the emission change should be the major driver for the PM_{2.5} concentration increase in Central Africa.



Figure 3. Spatial distribution of changes in projected global PM_{2.5} concentrations relative to the baseline period (2010–2019) under different climate change scenarios. Panels (a)-(d) represent the changes in PM_{2.5} concentration for 2030s (2021-2050 average), 2050s (2041-2070 average), 2070s (2061-2090 average), and 2080s (2071-2100 average) under SSP1-2.6 scenarios compared to the baseline condition. Panels (e)-(h) represent that of the same period but under SSP2-4.5. Panels (i)-(l) represent that of the same period but under SSP3-7.0. Panels (m)-(p) represent that of the same period but under SSP5-8.5.

We have added Figure S5 and Figure S6 into the supplementary material and provided an explanation in the revised manuscript (Lines 295–298):

" $PM_{2.5}$ concentrations continued to exceed baseline values in central Africa under SSP3-7.0 and SSP5-8.5, which is quite consistent with the emission-increasing trends in the region as shown in

Figure S22 and S23, implying that the emission change should be the major driver for the $PM_{2.5}$ concentration increase in Central Africa."



Figure S22. Changes in BC, NH₃, NOx, SO₂, and OC emissions (g km⁻² yr⁻¹ in log scale) under SSP3-7.0 scenario for 2030s (average of 2021-2050), 2050s (average of 2041-2070), 2070s (average of 2061-2090), and 2080s (average of 2071-2100) compared to that in 1990s (1981-2010).



Figure S23. Changes in BC, NH₃, NOx, SO₂, and OC emissions (g km⁻² yr⁻¹ in log scale) under SSP5-8.5 scenario for 2030s (average of 2021-2050), 2050s (average of 2041-2070), 2070s (average of 2061-2090), and 2080s (average of 2071-2100) compared to that in 1990s (1981-2010).

Are wildfire emissions included in the historical CMIP emissions data? They almost certainly are not included in the future SSP emissions data. The same is true for windblown dust. What are the implications of these limitations for the analysis?

Authors' response: The wildfire emissions, defined as the emissions from forest, grassland, and peatland fires, along with agricultural waste burning (AWB) on fields, have been included in the historical CMIP6 gridded emissions dataset. The development of the historical open burning emissions in CMIP6 can be found in Marle et al. (2017).¹² CMIP6 also contains the future open burning emissions which are derived from integrated assessment models (IAMs). However, unlike historical open burning emissions, the spatial distribution of open burning emissions of a given category (e.g., forest burning) within each country does not vary in future scenarios.¹³

The wind-blown dust emission has not been included in this study due to the relatively coarse resolution (100km) and large uncertainties of dust emission in the CMIP6 dataset.¹⁴ The deficiency of dust emissions may have an influence on our results, especially for the Sahara and Middle East, which are close to large sources of dust emissions. However, wind-blown dust has a limited impact on our health burden assessment due to the fact that these areas only contain small number of the population. In addition, a study conducted in Spokane found that particulate matter, composed mostly of dust, generally had limited association with premature mortalities.¹⁵

We have added more descriptions of CMIP6 emissions in the manuscript from Line 101 to Line 104.

"Covering the period of 1750–2100 (historical dataset: 1750–2014, future emissions dataset: 2015– 2100), CMIP6 gridded emissions dataset includes aviation emissions, all other anthropogenic emissions sectors, and total open burning emissions. This gridded dataset has previously been used for global model simulation and for emission scenarios comparisons.^{48, 49}"

For the implications of these limitations, we have discussed more in the revised manuscript (Lines 488–494).

"Finally, the biases in emissions data (e.g., bias in future wildfires and missing windblown dust), can be directly propagated to the air pollution concentration estimation. Thus, $PM_{2.5}$ projections in this work contain unavoidable uncertainty. The spatial pattern of windblown dust was not included in this study, which may have an influence on our results, especially for the Sahara and Middle East. Given the proximity of these regions to large sources of dust emissions, there is a possibility that an underestimation of $PM_{2.5}$ concentrations would occur in these regions. However, the impact on the mortality estimations is limited since these regions are more sparsely populated."

<u>3. Reviewer #2 comment:</u> Finally, there is not much discussion as to the meaning or utility of these results. Ultimately, the authors conclude that SSP1-2.6 produces the lowest $PM_{2.5}$ concentrations and would lead to a significantly reduced mortality burden. This seems rather weak: policymakers and the scientific community do not need this paper to reach that conclusion. One possibility would be to extend the mortality burdens to consider costs and compare this to estimates of costs for controls needed to reach different SSP scenarios.

Authors' response: Thank you for your comments. In our revised manuscript, we have highlighted the meaning of our work. We have calculated the economic impact of $PM_{2.5}$ -related mortality as suggested by the reviewer in Text S9. (SI Page 8–10)

Lines 442–453:

"From the methodology and dataset perspectives, this work provides a new set of global-scale future $PM_{2.5}$ dataset in 10km spatial resolution. This dataset can be used by others for air quality-related studies at the national and even regional scales. The dataset can be downloaded from the link listed in Text S11. The method developed in this work can also be implemented for other air pollution-related research. Researchers can further develop other more advanced deep learning frameworks for relevant studies based on the design of the method proposed in this work.

From the results perspective, this work has quantified how the future $PM_{2.5}$ and its associated adverse health impacts will change based on different SSP scenarios. Based on our results, governments and relevant stakeholders from different countries can generally understand to what extent can $PM_{2.5}$ influence their specific local health burdens. This can provide useful scientific references for future air pollution control policy design. In addition, when other studies come out in the future, the results from this work can also be used for the comparison. For example, compared to the adverse effects caused by other pollutants, such as O_3 , which pollutant should the government put onto the priority position under different SSP scenarios." We agree with the reviewer that it is also important to present the results from the economic loss perspective. We have calculated the economic burdens caused by future PM_{2.5} pollution, as shown in Text S9. The health-economic impact has been discussed from Line 454 to Line 461 in the manuscript. *"From the health-economic impact perspective, the results of economic burdens shed light on the relationship between mortality cost that is associated with PM_{2.5} pollution and economic development in various countries under different future scenario. The economic burdens related to future PM_{2.5} pollution are discussed in Text S9. Figure S18 and Figure S19 show the economic loss that is associated with PM_{2.5}-related health burdens. SSP3-7.0 and SSP5-8.5 scenarios result in the lightest and heaviest economic loss, respectively. As shown in Figure S19, for most OECD countries, China, and Central Asia, air pollution mitigation and economic development can have a beneficial synergistic effect. The ratio of economic loss associated with PM_{2.5} pollution to the total GDP (PPP based) is minimal in the sustainable development scenario (SSP1-2.6). For Central Africa and South America, from PM_{2.5} associated economic loss perspective, these countries may consider choosing SSP2-4.5 pathway as their development modes."*

Text S9. Health-economic impact

The cost of premature deaths is estimated from the value of statistical life (VSL). VSL is a measure of how much that individuals are willing to pay for a reduction in the risk or likelihood of premature death. ⁵² This methodology has been applied by the World Bank and IHME (2016)⁵³ to estimate the economic loss that is associated with air pollution. The proposed benefit-transfer function is shown below:

$$VSL_{c,n} = VSL_{OECD} \times \left(\frac{Y_{c,n}}{Y_{OECD}}\right)^{\epsilon}$$
 Eq. (S9)

where $VSL_{c,n}$ is the estimated VSL for country c in year n, VSL_{OECD} is the average base VSL in Organisation for Economic Co-operation and Development (OECD) countries (\$3.83 million), $Y_{c,n}$ is Gross Domestic Product (GDP) per capita based on Purchasing Power Parity (PPP) in country c in year n, Y_{OECD} is the average GDP per capita based on PPP for the OECD countries (\$37,000), and \in is the income elasticity (1.2 for low- and middle-income countries and 0.8 for high-income countries). \in is assumed as constant over the future scenarios in line with other literatures.^{16, 17} The economic loss that is associated with the $PM_{2.5}$ pollution for country c in year n can be calculated as follow:

$$Cost_{c,n} = M_{c,n} \times VSL_{c,n}$$
 Eq. (S10)

The economic burden of premature death (Eco_{burden}) on the overall economy of the country can be calculated as follows:

$$Eco_{burden} = \frac{Cost_{c,n}}{GDP_{c,n}} \times 100\%$$
 Eq. (S11)

where $M_{c,n}$ is the $PM_{2.5}$ -associated premature mortality, $GDP_{c,n}$ is the country's total GDP (PPP based). GDP (PPP based) for different future scenarios at national level can be obtained from https://tntcat.iiasa.ac.at/SspDb/dsd?Action=htmlpage&page=citation, which is produced by the OECD Env-Growth model.

As shown in Figure S31, for almost all of the representative regions, the SSP3-7.0 and SSP5-8.5 scenarios result in the lightest and heaviest economic costs, respectively. The global cost of $PM_{2.5}$ -related mortality burdens will reach 8.9×10^7 (95% CI: $6.3 - 11.2 \times 10^7$) million USD by 2100 for the SSP5-8.5 scenario, but only 2.2×10^7 (95% CI: $1.5 - 2.7 \times 10^7$) million USD for SSP3-7.0. Even though SSP3-7.0 is the scenario with the highest premature mortalities, it has the lowest economic losses given that its income level is much lower than the other scenarios.

Figure S32 represents the ratio of economic loss caused by PM_{2.5}-related mortality to the total GDP (PPP based) for each country, indicating the extent to which can the PM_{2.5}-associated health burden affect the national economy. For most OECD countries, China, and Central Asia, air pollution mitigation and economic development can have a beneficial synergistic effect. In the sustainable development scenario (SSP1-2.6), the ratio of economic loss that is associated with PM_{2.5} pollution to the total GDP (PPP based) is minimal. By 2100, the ratios of the economic burdens that are associated with PM_{2.5} pollution to total GDP (PPP based) are lower than 6%, 12% and 8% for OECD countries, China, and Central Asia, respectively. However, as shown in Figure S32, the economic burdens for Central Africa and South America under SSP1-2.6 scenario are quite excessive when compared with the overall GDP (PPP based). By incorporating the factors of economic growth and economic loss associated with PM_{2.5} pollution, these countries may consider choosing SSP2-4.5 pathway as their development mode.



Figure S31. Economic loss caused by PM_{2.5}-related mortality over different regions around the world for SSP1-2.6, SSP2-4.5, SSP3-7.0, and SSP5-8.5 scenarios (Units: million US\$).



Figure S32. The ratio of economic loss caused by PM_{2.5}-associated premature mortality to the total GDP (PPP based) for each country. The first row represents the ratios in the 2010s. (Units: %).

Minor comments by line number

<u>1. Reviewer #2 comment:</u> Line 68 conscientious is not the right word here. Perhaps the authors mean "comprehensive".

Authors' response: Thank you very much. We have revised the word "conscientious" to "comprehensive". (Line 69)

2. Reviewer #2 comment: Line 116, 147, 154: "well-trained" should be just be "trained".

Authors' response: Thank you. We have corrected "well-trained" to "trained".

<u>3. Reviewer #2 comment:</u> 158: "the model gave a well-fitted in the areas": this phrase is missing a noun ("estimate" or "result"). Alternatively, "The results show that the model produced good fits in areas with both ...". Reading this a few times, I believe it is the case that this section refers to how well the model reproduces the training data. Are the values shown in Figure S2 averages across all months for all 17 years?

Authors' response: Thank you for your comments. We are sorry for the typo, and we have corrected the sentence in the manuscript. (Line 198–199)

"The results show that the model produced good fits in the areas with both low ($\leq 35 \ \mu g/m^3$) and high (> 35 $\mu g/m^3$) PM_{2.5} concentration."

Yes, Figure S2 presents the monthly comparison between satellite-retrieved $PM_{2.5}$ data and the average 8-fold cross-validation data predicted using the U-net convolutional neural network for the years of 1998-2014. We have revised the caption of Figure S2 (Figure S5 in the revised SI).

"Figure S5. Monthly spatial comparison between satellite-retrieved PM_{2.5} data and the average 8-fold cross-validation data predicted using the U-Net convolutional neural network for the years of 1998-2014."
<u>4. Reviewer #2 comment:</u> 160-161: are these stated results ("all grid cells within +/- 12 ug/m3") true for all months, or just for the long-term averages?

Authors' response: Thank you for your comment. This sentence means the monthly average during the period of 1998 to 2014. We have revised the sentences in Line 199–201 and Figure S6–S7.

"As demonstrated in Figures S6 and S7, the errors between the simulated and target monthly average $PM_{2.5}$ concentrations for all grid cells were within $\pm 12 \ \mu g/m^3$ for 1998-2014. The monthly average relative errors specific to each country were within $\pm 10\%$."

"Figure S6. Absolute error between monthly satellite retrieved PM_{2.5} and the data predicted by using U-net convolutional neural networks for 1998-2014

Figure S7. Country-specific relative error between annual satellite retrieved PM_{2.5} and the data predicted by using U-net convolutional neural networks"

5. Reviewer #2 comment: 165-167 There is no need to put these statistics in both the text and in Table1. Four significant digits seems too many.

Authors' response: Thank you for the comment. We have shortened the significant digits in Table 1 (as shown below) and delated the statistics in the text.

We have revised the sentence to:

"The statistical evaluation metrics (A1-A6 in the supplemental material) shown in Table 1 were further used to verify the model performance."

	NMB*	NME*	MB* (μg/m ³)	MAGE* (µg/m ³)	RMSE* (µg/m ³)	R
Average	-0.01	0.22	-0.05	1.36	4.02	0.987
Standard error	0.01	0.03	0.08	0.11	0.39	0.010

Table 1. 8-fold cross-validation of U-Net CNN model performance

*NMB: normalized mean bias; NME: normalized mean error; MB: mean bias; MAGE: mean absolute gross error;

RMSE: Root Mean Squared Error

6. Reviewer #2 comment: 167-168: how do you determine whether the model is or is not overfitted?

Authors' response: The model we proposed in this study can overcome the overfitting issue. First, from the model design perspective, we utilized the data augmentation and dropout layer in each block of the U-Net CNN structure. Data Augmentation is a technique to extend the training data by using flipping, rotating, scaling, etc., so that the generalization ability can be improved by increasing the diversity of learning samples.¹⁸⁻²⁰ In our work, the specific operations of data augmentation were to randomly rotate 2D-array images with a rotation angle ranging from -10 degrees to 10 degrees, and to flip 2D-array images with 50% probability randomly.

The dropout layer is able to reduce overfitting in the deep neural network model. Dropout strategy solves the overfitting problem from two main aspects.²¹ One is to drop units from neural networks and average them randomly. The dropout regularization is to randomly discard units (together with their connections) from the neural network during training in each iteration. When different sets of units are dropped, it is equivalent to training a different neural network. Thus, the dropout procedure is like averaging the effects of a large number of different networks. This strategy is often effective in preventing overfitting problems. ^{22, 23} The second is to reduce the complex co-adaptation relationship between different units. The dropout regularization allows hidden units to be randomly omitted from the network, so that a hidden unit cannot depend on the existence of other hidden units. In this way, the update of weights no longer relies on the co-adaptation relationship between different units, which forces the network to learn more robust features. If our neural network targets to make predictions, it should not be too sensitive to some specific cue fragments, and it should be able to learn some common patterns from many other cues (robustness).^{24, 25} Srivastava et al.(2014)²¹ compared the performance of dropout with other techniques and found that the dropout strategy could reduce the generalization error effectively, a measure of how accurately an algorithm is able to predict results for data not previously involved in training.

In addition, as shown in Figure S4, the monotonic decrease in training and validation loss shows that our model is not overfitted.

The overfitting issue and generalization ability of our model have been discussed in the manuscript from Line 135 to Line 137.

"The data augmentation and dropout regularization have been applied to improve the model generalization ability, as discussed in Text S7. And the monotonic decreases in training and validation loss (Figure S4) have proved that no overfitting was detected."



Figure S4. Illustration of training loss and validation loss.

Text S3. Generalization ability of deep learning model

In this work, data augmentation and regularization technique were used to improve the model generalization. Data Augmentation is a technique to extend the training data by using flipping, rotating, scaling, etc., so that the generalization ability can be improved by increasing the diversity of learning samples and increasing the difficulty of learning samples. ¹⁸⁻²⁰ Taylor and Nitschke (2018)²⁶ conducted a comparative study on the effectiveness of geometric and photometric (color space) transformations, showing that flipping, rotating, and color jittering can improve the accuracy of the results by 2.86%, 4.91%, and 2.68%, respectively. In our work, the specific operations of data augmentation were to randomly rotate 2D-array images with a rotation angle ranging from -10 degrees to 10 degrees, and to flip 2D-array images with 50% probability randomly.

Compared with data augmentation, the dropout strategy is a type of regularization technique. The dropout layer within the model is able to reduce the overfitting and thus improve the generalization ability in the deep neural network model. Srivastava et al.(2014)²¹ compared the performance of the dropout method with other techniques and found that the dropout strategy could reduce the

generalization error effectively, a measure of how accurately an algorithm is able to predict results for data not previously involved in training. Thus, dropout regularization has proven to be successful in reducing overfitting.

Equipped with data augmentation and regularization, our network can predict the $PM_{2.5}$ concentration in the future scenario better, even if the data in the future scenario are slightly different from the training input data.

<u>7. Reviewer #2 comment:</u> 188-193: Is there enough variability in the test dataset (2015-2019) to represent changes to 2100? Alternatively, are the changes in meteorological and emissions inputs under the SSPs outside the range of the training data?

Authors' response: Thanks for your comment. This is a good point and requires a lengthy explanation as described below. On the one hand, our results are based on the underlying assumption that the relationship between $PM_{2.5}$ concentrations and other independent variables (e.g., meteorological factors and emission) in the historical period is also suitable for future scenarios. In other words, this study assumes that the current atmospheric physical and chemical mechanisms also hold for future scenarios.

On the other hand, deep learning models have strong generalization ability, which refers to the ability to adapt to new data with similar distributions as the ones used to create the models. Dinal et al. $(2017)^{27}$ and Kawaguchi et al. $(2017)^{28}$ provide theoretical insights into why and how deep learning can generalize well on previously unseen data. To improve the model generalization, we applied data augmentation and dropout regularization in this work, as discussed in Text S3. Equipped with data augmentation and regularization, our network can predict the PM_{2.5} concentration in the future scenario better, even if the data in the future scenario are slightly different from the training input data.

We plotted the data distribution of the training dataset and inputs for the period of 2071-2100 under the four SSPs as an example. We have described the dataset distributions in Text S1.

Text S1. Frequency distribution of current and future data

Figure S1 and Figure S2 show the frequency distributions of current and future meteorological and emission data. For the meteorological inputs in Figure S1, overall, the distributions for current and

future scenarios are similar. For example, the PBLH within the ranges of 350m to 1200m appears in high frequency under current and future scenarios. The temperature and specific humidity under current and future scenarios are skewed to the right and contain similar distribution patterns.

For emissions inputs, since the difference between the maximum (up to 8×10^6 g km⁻² yr⁻¹) and minimum (0 g km⁻² yr⁻¹) values is very large, in order to be able to compactly display numerical data with such a wide range of values, we used logarithmic scale here to present the distribution. In Figure S2, the change in OC emission is the most noticeable and the peaks in future scenarios tend to shift towards higher values. However, overall, few significant changes were found in the shape of the distribution (peaks, symmetry, skewness, uniformity) for either meteorology or emission input. Therefore, although the values between current periods and future scenarios differ, the distribution variations are subtle, and the U-Net deep learning model applied in this work has the capability to digest the data of future scenarios.





Figure S3. Frequency distribution of meteorological inputs for the four SSPs in the 2080s (2071-2100) compared with the training dataset (1998-2014). The x-axis corresponds to the value of meteorological inputs, and the y-axis represents the frequency counts falling in each interval. Units for the x-axis of PBLH, temperature, specific humidity, wind speed, and sea level pressure are m, °C, kg/kg, m/s, and kPa, respectively.



Figure S4. Frequency distribution of emission (g km⁻² yr⁻¹ in log scale) for the four SSPs in the 2080s (2071-2100) compared with the training dataset (1998-2014). The x-axis corresponds to the value of emission inputs in the log scale, and the y-axis represents the frequency counts falling in each interval. Units for the x-axis are g km⁻² yr⁻¹ in log scale.

<u>8. Reviewer #2 comment:</u> 208-209 This study is using future climate and emissions projections to estimate future air quality. Both emissions and climate are changing. In order for the authors to attribute the increases in $PM_{2.5}$ at mid-century under SSP5-8.5 specifically to "climate change", they should show that emissions changes are not affecting the concentration changes in central Africa.

Authors' response: We agreed with the reviewer that both future climate and emissions will change under the SSP5-8.5 scenario, leading to the changes in $PM_{2.5}$. We have revised the description in the manuscript. (Line 292–293)

"Thus, in the middle of the 21st century, climate and emission change would considerably increase $PM_{2.5}$ concentrations and cause considerable damage to human health in central Africa."

<u>9. Reviewer #2 comment:</u> 213-216 This sentence does not make sense. What asymmetry is being referred to, and how is it disproportionate? "Intimidation" is clearly not the word the authors intend, but I am unable to tell what is intended.

Authors' response: We apologize for causing the misunderstanding.

The meaning we intended to convey is as follows. Due to the urbanization process, residents usually gather in the city where $PM_{2.5}$ concentration is relatively high.^{29, 30} Since a large percentage of people are living in urban areas, using the average $PM_{2.5}$ concentration of rural and urban areas cannot reveal the exact population exposure level.

We have revised the sentences in the manuscript from Line 300 to Line 304 and added the population density (persons/km²) in the SI (Page 31).

"SSPs narratives gave rise to spatial and temporal differences in the demographic projections. The projected population density (persons/km²) and the corresponding variations (compared to the situation in the 2010s) in four SSP scenarios are shown in Figure S26. Combined with demographic projections, the exposure concentration can be estimated and used to assess the $PM_{2.5}$ exposure associated health impacts.^{31, 32}"



Figure S26. (a)–(d) Projected population density (Persons for 25+ years/km²) for the four SSPs in the 2091-2100, and (e)–(g) corresponding projected population change compared with that in 2010s (2010-2019 average).

<u>10. Reviewer #2 comment:</u> 217-230 and Fig 4: I believe the authors are using the word "exposure" to mean population-weighted $PM_{2.5}$ concentrations. If so, please state this is the case. The authors use the term "population-weighted" on line 225 but it is not clear whether this is intended to be synonymous with the earlier definition of "exposure".

Authors' response: Thanks for your comment. Yes, the "population-weighted" is used to represent "exposure" in this study. To clarify, we have added the description and calculation results of "exposure" in Text S5. (SI Page 6)

"Population-weighted concentration can better reflect the impact of $PM_{2.5}$ pollution on the exposed population, and thus build a more reliable theoretical basis for public health assessment. Eq. (S5) and Eq. (S6) were used to calculate the exposure concentration ($C_{PM_{2.5}}^{i-pop}$) and spatially averaged ambient levels ($C_{PM_{2.5}}^{i-space}$) of $PM_{2.5}$, respectively.

$$C_{PM_{2,5}}^{i-pop} = \left(\sum_{k=1}^{N} C_k^i * P_k^i\right) / \sum_{k=1}^{N} P_k^i \qquad Eq. (S5)$$

$$C_{PM_{2.5}}^{i-space} = \frac{1}{N} \left(\sum_{k=1}^{N} C_k^i \right)$$
 Eq. (S6)

Here, different countries and the total grid number of the country are represented by i and N, respectively. C_k^i and P_k^i are the $PM_{2.5}$ concentration and corresponding population of grid k in country i, respectively."

<u>11. Reviewer #2 comment:</u> 223-224 "Space-weighted" should be "Spatially-averaged". More importantly, the claims that $PM_{2.5}$ concentrations are lower under SSP5-8.5 than under SSP2-4.5, and that this is due to tighter pollution controls in the former, are counterintuitive. My understanding is that air pollutants are often co-emitted with CO_2 during combustion, so that scenarios in which CO_2 emissions are reduced tend to have lower air pollutant emissions also. Please expand on this point, or provide a reference, or possibly additional figures in the SI showing changes in emissions of the species considered in your model.

Authors' response: Thanks for your comments. We have corrected the word "space-weighted" to "spatially-averaged" in the revised manuscript.

It should be noted that unlike the general greenhouse gases (GHG), such as CH₄ and CO₂, aerosols and their precursors (BC, OC, NH₃, NOx, SO₂) are short-lived climate forcers (SLCFs) pollutants, with lifetimes ranging from minutes to weeks. Therefore, the impacts of SLCFs on radiative forcing are relatively limited. In contrast, these SLCF pollutants are often tied to regional air quality and can be effectively controlled. Decisive and rapid action to address SLCF pollutants will have an immediate

impact on improving air quality. As described in the IPCC AR6 report, in the SSP scenarios, SLCF emissions trajectories are steered by different levels of air pollution controls, independently from climate change mitigation (i.e., GHG mitigation).³³ Thus, the emission trajectories of SLCF in the SSPs scenario are independent of CO₂ emissions. In the SSP5-8.5 scenario, extremely stringent pollution control policies will be implemented for SLCFs control.³⁴

SSP5-8.5 shows a transition to less polluting fuels and technologies, leading to a rapid and sustained reduction in emission intensities of air pollutants. SSP2-4.5, on the other hand, emphasizes large-scale electrification and modest technology advances. As illustrated by Rao et al.(2017), SSP2 shows a continued decline in all pollutants throughout the century, while SSP5 exhibits a faster decline due to more effective pollution controls resulting in the lowest emissions of air pollutants in the second half of the century. ³⁴

We have further added a summarized table of key differences among the four SSP scenarios relevant to air pollution in Table S5 in the supplemental material. We have also provided below figures (Figure S13 – Figure S17) to reveal the emission changes under different scenarios.

Table S5. Descriptions of the critical elements for SSP1-2.6, SSP2-4.5, SSP3-7.0, and SSP5-8.5relevant to air pollution

Scenario	Description	Land-use Change Regulation	Environmental Development	Pollution Control Policy	Energy Tech Change	Population Growth
SSP1-2.6	Sustainability	Strong regulation to avoid environmental tradeoffs	High environmental awareness; more inclusive development that respects perceived environmental boundaries	Strong	Directed away from fossil fuels, toward efficiency and renewables	Relatively Low
SSP2-4.5	Middle-of- the-road	Medium regulation; slow decline in the rate of deforestation	Medium environmental awareness; work toward but make slow progress in achieving sustainable development goals	Medium	Some investment in renewables but continued reliance on fossil fuels	Medium
SSP3-7.0	Regional rivalry	Limited regulation; continued deforestation	Low environmental awareness; strong environmental degradation in some regions	Weak	Slow tech change, directed toward domestic energy sources	High in developing countries; low in industrialized countries
SSP5-8.5	Fossil-fueled development	Medium regulation; slow decline in the rate of deforestation	High environmental awareness; local environmental problems are successfully managed	Strong	Directed toward fossil fuels; alternative sources not actively pursued	Relatively Low



Figure S13. Changes in SO₂ emission (g km⁻² yr⁻¹ in log scale) for 2030s (2021-2050 average), 2050s (2041-2070 average), 2070s (2061-2090 average), and 2080s (2071-2100 average) compared to that in 1990s (1981-2010) under the four scenarios.



Figure S14. Changes in NH₃ emission (g km⁻² yr⁻¹ in log scale) for 2030s (2021-2050 average), 2050s (2041-2070 average), 2070s (2061-2090 average), and 2080s (2071-2100 average) compared to that in 1990s (1981-2010) under the four scenarios.



Figure S15. Changes in OC emission (g km⁻² yr⁻¹ in log scale) for 2030s (2021-2050 average), 2050s (2041-2070 average), 2070s (2061-2090 average), and 2080s (2071-2100 average) compared to that in 1990s (1981-2010) under the four scenarios.



Figure S16. Changes in BC emission (g km⁻² yr⁻¹ in log scale) for 2030s (2021-2050 average), 2050s (2041-2070 average), 2070s (2061-2090 average), and 2080s (2071-2100 average) compared to that in 1990s (1981-2010) under the four scenarios.



Figure S17. Changes in NOx emission (g km⁻² yr⁻¹ in log scale) for 2030s (2021-2050 average), 2050s (2041-2070 average), 2070s (2061-2090 average), and 2080s (2071-2100 average) compared to that in 1990s (1981-2010) under the four scenarios.

<u>12. Reviewer #2 comment:</u> 239-247 The tenor of this paragraph is strange, especially "emerge victorious". The differences between scenarios are significant, even if they are not very different in terms of the fraction of the population meeting the WHO's stringent 5 ug/m3 AQ guideline.

Authors' response: We agree with the reviewer, and we have reworded the paragraph and emphasized the difference between scenarios. (Lines 339–346)

"The proportion of the population that would be exposed to the $PM_{2.5}$ concentration below previous and current Air Quality Guideline (AQG) values is also estimated under future climate change scenarios. As shown in Figure S29, the differences between SSP1-2.6 scenario and the other three scenarios are considerable. Compared with the other three scenarios, SSP1-2.6 would result in the largest fraction of the population exposed to the $PM_{2.5}$ level that is lower than 5 µg/m³. In the SSP1-2.6 scenario, 3.5% of the world's population will live in areas that have $PM_{2.5}$ concentrations lower than 5 µg/m³ by 2100, which is well above the baseline (2.0%). The other scenarios are comparable in terms of the proportion of the population exposed to the $PM_{2.5}$ concentration that is below the current AQG values."

<u>13. Reviewer #2 comment:</u> 254-255 The text and the caption to Fig S19 indicates that the first row shows baseline PM2.5 mortality burden for 2010s, but the titles of the plots suggests otherwise. The caption to Fig 5 says "premature mortality rate"; a mortality rate usually means "mortalities per 100k" or similar. If instead the authors intend "rate" to mean "per year", then please state that.

Authors' response: We apologize for the mistake and Figure S19 has been revised (Figure S30 in the revised SI). We also corrected the caption for Fig. 5.

*"Figure 5. PM*_{2.5}*-associated premature deaths (> 25 years old) in different regions. The red bars represent premature deaths, and the vertical black lines indicate the 95% empirical confidence intervals."*



Figure S30. Projected premature mortality rate (per 100,000 population) in 184 countries under four SSP scenarios. The first row represents the baseline mortality rate in the 2010s.

<u>14. Reviewer #2 comment:</u> 259-269 The number of significant digits given for PM2.5-associated mortalities is unscientifically precise.

Authors' response: We have revised the significant digits in Lines 377–389.

"Given the middle-road development pattern of SSP2-4.5, premature deaths in this scenario would peak at 9,024,000 (95% Confidence Interval (CI): 6,352,000–11,236,000) in the 2060s and then steadily decline to 7,394,000 (95% CI: 5,202,000–9,291,000) in the final decade of the century, which is a less rapid decline than in the SSP1-2.6 scenario. SSP3-7.0 assumes weak pollution control in which the implementation of pollution mitigation measures is delayed and less ambitious in the long term. In this scenario, premature deaths would spike dramatically in all regions except North America, *Europe, and Russia and would not decrease until the end of the century. The global number of PM*_{2.5}associated premature deaths would reach 11,149,000 (95% CI: 7,877,000–13,800,000) in 2091–2100, an increase of 63% from the baseline period. In the SSP5-8.5 scenario, which emphasizes technological progress and rapid economic growth through human capital development, environmental issues become a priority health concern, and ambitious air quality goals result in pollutant levels well below current levels in the medium to long term.^{16,72} Therefore, in SSP5-8.5, global premature deaths would peak at 8,509,000 (95% CI: 5,981,000–10,617,000) in the 2040s and then decline to 6,258,000 (95% CI: 4,410,000–7,887,000) in the second half of the 21st century as high-performance pollution control technologies are developed. This decrease would result in a smaller premature death burden than in the baseline period."

<u>15. Reviewer #2 comment:</u> 285-287 This sentence appears to be referring to the numbers in the first row of Table S4, which are all positive. These are for SA1, which is described as a "constant population" scenario, but the text indicates it is considering only population changes. This is contradictory. If population changes are exacerbating the burden of premature deaths, then the values from the table (holding population constant) should be negative.

Authors' response: We apologize for the typo, and we have revised the statement in Lines 409–411.

"In the first sensitivity experiment (SA1), the only contributor to the difference in the estimated premature deaths from the baseline period is the demographic transition, while the contributor to the difference in the second sensitivity experiment (SA2) is the $PM_{2.5}$ variation."

<u>16. Reviewer #2 comment:</u> 293-294 This sentence says SA2 is assuming constant population distribution, the opposite from what is written in 282-284.

Authors' response: We apologize for this mistake, and the statements in Lines 409–411 have been corrected.

"In the first sensitivity experiment (SA1), the only contributor to the difference in the estimated premature deaths from the baseline period is the demographic transition, while the contributor to the difference in the second sensitivity experiment (SA2) is the $PM_{2.5}$ variation."

Technical Corrections

Several references are being generated incorrectly by your reference software.

The authors of ref 2 are given as "Collaborators, G.R.F."

Ref. 33 appears to have an additional reference embedded within it.

Refs 50-56 appear to be using just the first initials for the journal titles.

Authors' response: We are sorry for the typo, and it has been corrected.

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Comments on Supplement

<u>1. Reviewer #2 comment:</u> Table S4: Suggest adding "(constant population)" and "(constant air pollution)", or similar, under the names SA1 and SA2 (though these designations appear to be reversed). There are far too many significant digits included in this table. Clarify whether "baseline" here refers to the 2010-2020 period or whether it refers to the "base" (non-sensitivity analysis) simulation.

Authors' response: Thanks for your comment. The "baseline" refers to the 2010-2019 period. We have revised Table S4 to adjust the significant digits and make it clear.

Table S8. Changes in projected premature deaths (> 25 years old) for two sensitivity studies (SA1and SA2) relative to the premature deaths in the baseline period (2010-2019). Values are in 1000s.

	Time frame	SSP1-2.6	SSP2-4.5	SSP3-7.0	SSP5-8.5
	2021–2040	1594.31	1458.18	1340.62	1581.58
SA1*	2041–2060	3016.17	2916.32	2829.60	3000.95
(constant air pollution)	2061–2080	3214.96	3550.96	4024.10	3228.01
r)	2081-2100	2398.21	3505.78	5151.04	2483.66
	2021–2040	-521.75	-50.25	403.24	-282.53
SA2*	2041–2060	-1819.82	-688.96	205.40	-1089.66
(constant population)	2061–2080	-2583.48	-1129.58	-225.21	-1642.07
r - r)	2081-2100	-3083.89	-1800.52	-607.03	-2236.05

*SA1 focused on the impact of future demographic changes on the number of premature deaths.

*SA2 targets quantifying the future changes in the premature mortality burden due to climate change and emissions.

2. Reviewer #2 comment: Figure S9: There appears to be almost the same pattern in each panel. Recommend checking closely for a scripting error. Also, this strikes me as a very large decrease in average wind speeds, much larger than I have seen in my own climate modeling.

Authors' response: Thanks for your comment. We apologize for the script mistake, and Figure S9 of the wind speed comparison has been replotted in the SI (Page 22).



Figure S12. Changes in multi-model ensembles of surface wind speed using delta change downscaling for 2030s (2021-2050 average), 2050s (2041-2070 average), 2070s (2061-2090 average), and 2080s (2071-2100 average) compared to that in 1990s (1981-2010).

<u>3. Reviewer #2 comment:</u> Fig S14: Change the y-axis on so that it is units of billions, so that you can show 5.0, 5.5, etc., rather than repeating "5E+09" twice.

Authors' response: Thanks for your suggestions. We have changed the y-axis in Figure S24.



Figure S24. Total population size (values in billion) aged 25 years and above for major world regions under SSP1-2.6, SSP2-4.5, SSP3-7.0, and SSP5-8.5 until the end of the 21st century.

<u>4. Reviewer #2 comment:</u> Fig S17: What are the units of population growth rate? Percent per year? It's striking that on this scale North America is the same for all scenarios and times despite significant variation shown in Fig S15. Perhaps instead of showing the growth rate, the authors should show the population density at selected time points for each SSP.

Authors' response: Thanks for your comments.

The population growth rates for the decadal mean population compared to that in the 2010s (2010-2019 average) are calculated by using the following formula. The units are persons/persons.

$Population growth rate = \frac{Future \ decadal \ country_level \ pop. - 2010s \ pop.}{2010s \ pop.}$

In fact, the population growth pattern in North America and three countries in North America (Canada, U.S.A., and Mexico) is different in the four future SSP scenarios, as shown in Table A1-A4.

Table A1. Population aged 25 years and above (values in million) in North America (the sum ofCanada, Mexico, and U.S.A.) under the four SSP scenarios.

	Baseline	2020s	2030s	2040s	2050s	2060s	2070s	2080s	2090s
SSP1-2.6	312.0	353.3	392.8	425.8	453.3	476.9	495.2	503.8	500.4
SSP2-4.5	312.0	349.6	384.6	413.9	439.8	462.9	481.9	495.4	503.4
SSP3-7.0	312.0	341.9	367.3	383.7	393.4	399.6	401.8	399.2	393.9
SSP5-8.5	312.0	357.4	401.7	444.5	488.2	532.1	575.5	613.7	641.8

Table A2. Population aged 25 years and above (values in million) in Canada under the fourSSP scenarios.

	Baseline	2020s	2030s	2040s	2050s	2060s	2070s	2080s	2090s
SSP1-2.6	25.9	29.6	32.8	36.1	39.1	41.6	43.5	44.3	43.7
SSP2-4.5	25.9	29.3	32.1	34.8	37.3	39.4	41.2	42.4	42.7
SSP3-7.0	25.9	27.9	29.2	29.8	29.5	28.7	27.6	25.9	24.0
SSP5-8.5	25.9	30.6	35.0	40.0	45.5	50.9	56.1	60.4	63.1

	Baseline	2020s	2030s	2040s	2050s	2060s	2070s	2080s	2090s
SSP1-2.6	217.5	244.6	269.5	291.5	312.1	332.3	350.1	361.5	364.9
SSP2-4.5	217.5	241.9	263.2	281.3	298.6	315.6	330.0	340.6	347.7
SSP3-7.0	217.5	234.3	246.5	251.3	250.7	247.8	241.0	229.8	216.1
SSP5-8.5	217.5	249.5	279.9	311.9	348.3	387.6	428.2	466.0	497.3

 Table A3. Population aged 25 years and above (values in million) in U.S.A under the four SSP scenarios.

 Table A4. Population aged 25 years and above (values in million) in Mexico under the four SSP scenarios.

	Baseline	2020s	2030s	2040s	2050s	2060s	2070s	2080s	2090s
SSP1-2.6	68.7	79.1	90.5	98.2	102.1	103.0	101.6	98.1	91.8
SSP2-4.5	68.7	78.5	89.2	97.8	103.9	107.9	110.7	112.4	113.0
SSP3-7.0	68.7	79.7	91.6	102.6	113.3	123.1	133.2	143.4	153.8
SSP5-8.5	68.7	77.3	86.8	92.5	94.3	93.5	91.2	87.3	81.5

We agree with the reviewers that changes in population density need to be presented, as shown in Figure S26.



Figure S26. (a)–(d) Projected population density (persons for 25+ years old/km²) for the four SSPs in 2091-2100, and (e)–(g) corresponding projected population change compared with that in 2010s (2010-2019 average).

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1 Global PM_{2.5} prediction and associated mortality to 2100 under different climate

2 change scenarios

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- 14

Abstract

15 Ambient fine particulate matter (PM2.5) can cause severe adverse health impacts in humans. Thus, reducing PM2.5 16 exposure is an important public health focus. Meteorological and emissions factors, which considerably affect the 17 PM_{2.5} concentrations in air, vary significantly under different climate change scenarios. However, PM_{2.5} 18 concentrations and their associated disease burden under future climate scenarios are not well clarified. In this work, 19 the global PM_{2.5} concentrations from 2021 to 2100 were estimated by combining the U-Net convolutional neural 20 network deep learning technique, reanalysis data, emissions data, and bias-corrected Coupled Model Intercomparison 21 Project Phase 6 future climate scenario data. Based on the estimated PM_{2.5} concentrations, the future premature 22 mortality burden associated with PM2.5 exposure was assessed using the Global Exposure Mortality Model. Ambient PM2.5 exposure is expected to be highest in the SSP3-7.0 scenario and lowest in the SSP1-2.6 scenario in the major 23 24 representative regions of the world. The global mortality rate (per 100,000 exposed population) associated with PM2.5 25 under the four different scenarios (SSP1-2.6, SSP2-4.5, SSP3-7.0, and SSP5-8.5, ranging from 84.6 (95% Confidence 26 Interval (CI): 59.6–107.0) to 150.0 (95% CI: 106.2–185.0)) at the end of this century is expected to be lower than the 27 baseline (the 2010s, 161.1 (95% CI: 113.3-199.9)). Among all four scenarios, the sustainable development scenario 28 (SSP1-2.6) results in the lowest PM2.5 concentrations and the lowest premature mortality burden, which indicates that 29 this is the pathway that countries should strive for. Our work helps to advance the scientific understanding of the 30 global geo-climatic system and provides suggestions for scientists and policymakers.

31 Keywords: Climate change; Global; PM2.5; Mortality; Deep learning

- $32 \qquad \text{Synopsis: Future PM}_{2.5} \text{ pollution and its associated health burden have not been well clarified. In this study, a new }$
- 33 set of global-scale, spatially explicit $PM_{2.5}$ concentration from 2021 to 2100 with a spatial resolution of $0.1^{\circ} \times 0.1^{\circ}$
- 34 was estimated, and associated PM_{2.5} exposure and premature mortality burden was calculated.



Graphic for Table of Contents (TOC)

1. Introduction 37

38 Ambient particulate matter (PM2.5) poses a considerable global threat to human health. Exposure to outdoor PM2.5 39 caused 4.14 million deaths in 2019, accounting for 62% of all global deaths attributable to air pollution estimated by 40 the Global Burden of Disease Project.¹⁻⁴ Unmitigated climate change is projected to exacerbate inevitable challenges 41 and threats to global air quality and increase its attributable adverse health impacts.5-7 Therefore, it is necessary to 42 understand how future climate change scenarios will influence surface PM2.5 concentrations and propose appropriate 43 climate mitigation measures.

Most studies^{7,8} on PM_{2.5} concentration estimation under different climate scenarios have been based on the Coupled 44 45 Model Intercomparison Project 5 (CMIP5) Representative Concentration Pathways scenarios. However, with the 46 release of the CMIP6 simulation results, the Scenario Model Intercomparison Project provides new alternative 47 scenarios that are intimately connected with societal concerns regarding climate change mitigation, adaptation, and 48 impacts.9,10 Some studies have estimated future air quality based on CMIP6 climate projections;11,12 however, these studies either investigated the PM2.5 exposure in only one country or region, 11-13 or the predicted periods were shorter 49 than 50 years.^{14, 15} Although future global-scale PM_{2.5} simulations are available,^{12, 16} the low model spatial resolution 50 (e.g., $1.875^{\circ} \times 1.25^{\circ}$) prevents a clear understanding of how this pollutant will evolve over the next several decades 51 52 and hampers reliable estimations of how this pollutant will influence human health in the future. As yet, no 53 comprehensive study has estimated the global mortality burden associated with ambient PM2.5 based on high-54 resolution (e.g., 0.1° × 0.1°) and bias-corrected future climate projections that incorporate demographic and emissions 55 data. Such a study is urgently needed to understand how the PM2.5 concentration and the associated health burden in each country will vary under different climate scenarios. 56

57 In this study, we estimated $PM_{2.5}$ exposure and its associated mortality burden over the 2021–2100 period under the 58 SSP1-2.617, SSP2-4.518, SSP3-7.0,19 and SSP5-8.520 scenarios (SSP: Shared Socioeconomic Pathway). The 59 relationships between critical meteorological variables and PM2.5 concentrations were constructed using a U-Net convolutional neural network²¹ based on Modern-Era Retrospective Analysis for Research and Applications, version 60 2 (MERRA-2)²², CMIP6 global emissions data,²³ and satellite-retrieved PM_{2.5} data.²⁴ PM_{2.5} exposure and the 61 62 associated premature mortality over the 2021-2100 period were estimated based on the constructed relationships 63 between the PM2.5 concentrations, meteorological variables, emissions, the high-resolution and bias-corrected 64 CMIP6 future climate SSP scenario data (adjusted using the delta downscaling method), and future SSP demographic

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66 projections. Our work endeavored to elucidate how and through what pathways PM_{2.5} exposure would influence the 67 premature mortality burden in 184 countries and regions worldwide over the forthcoming 80 years, spanning the 68 space of challenges to mitigation and adaptation to climate change, which can exhibit a more expansive and 69 comprehensive_blueprint to air quality projection.

70 2. Methods

72

71 2.1. Data acquisition

2.1.1. Surface PM_{2.5} data for training

73 High-resolution and highly accurate global surface PM2.5 data are required to examine the relationships between 74 $PM_{2.5} \ concentrations \ and \ meteorological \ and \ emissions \ conditions. \ Therefore, \ global \ surface \ PM_{2.5} \ data \ at \ 0.1^{\circ} \times 0.1^{\circ}$ 75 combining AOD retrievals from the NASA MODIS, MISR, and SeaWIFS instrument, GEOS-Chem chemical 76 transport model, and ground-based observations calibrated by geographically weighted regression were selected for the study.²⁴ Compared with previous global surface PM2.5 concentration datasets,²⁵⁻²⁷ this set of PM2.5 values 77 contained finer resolution data and compensated for missing or limited monthly measurements. This PM2.5 dataset 78 79 was highly consistent with collocated ground-based observations from monitoring networks $PM_{2.5}$ ($R^2 = 0.84$), with 80 a root mean square error (RMSE) of 8.4 μ g m⁻³, and thus can accurately represent the surface PM_{2.5} concentrations.

81 2.1.2. Meteorological and emissions data for model input

To train the deep learning model, the following monthly average meteorological data were taken from the MERRAdataset:²⁸ surface temperature, wind speed, specific humidity, planetary boundary layer height, and sea level pressure; these parameters can strongly influence the PM_{2.5} concentration.²⁹ Several studies have contrasted the MERRA-2 dataset with ground-based observations and other reanalysis datasets and have shown that the MERRAdata better represent the surface meteorological conditions.^{22, 30-33} For example, when compared with the ground observation data from China, the RMSE, MB (mean bias), and R value for temperature were 3.62 K, -2.14 K, and 0.95, respectively.³³ These three statistical metrics for humidity were 5%, 0.63%, and 0.89.³⁴

- 89 Since the deficiency in the emissions of primary PM_{2.5} components (except organic carbon (OC) and black carbon
- 90 (BC)) in the CMIP6 datasets, future PM_{2.5} concentrations are driven by changes to precursor emissions (ammonia
- 91 (NH₃), nitrogen oxides (NOx), and sulfur dioxide (SO₂)), BC, OC and climate in this study. Global emission amounts
- 92 and percentages of the five species are presented in Table S1 and S2. Based on existing global emission inventory,

Deleted: Primary PM_{2.5} emissions data are not available in the CMIP6 dataset, we used the emissions of five pollutants (ammonia, nitrogen oxides, organic carbon, black carbon, and sulfur dioxide) as the emissions input for the deep learning model because these pollutants can have a marked influence on surface PM_{2.5} concentrations.^{35, 36}

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100 such as PKU-FUEL, primary PM2.5 emission has high correlation with the emissions of these five pollutants. 35, 36 101 Covering the period of 1750-2100 (historical dataset: 1750-2014, future emissions dataset: 2015-2100), CMIP6 102 gridded emissions dataset includes aviation emissions, all other anthropogenic emissions sectors, and total open 103 burning emissions. This gridded dataset has previously been used for global model simulation and for emission 104 scenario comparisons,^{13, 37, 38} CMIP6 dataset contains historical emissions (1750 to 2014) and future emission data 105 for SSP scenarios (2015-2100). CMIP6 emissions data were utilized in both the training and prediction processes. 106 CMIP6 historical emissions data (1998-2014, the historical emissions data are available till 2014) were used to build 107 the deep learning model, and the emission data of SSP scenarios for 2015 to 2019 were used in the deep learning 108 model verification process. Future emission data for 2021-2100 were input into the trained deep learning model for 109 prediction. The detailed narratives of emission inventory used in this study are summarized in Table S3.

110 The monthly MERRA-2 meteorological data and CMIP6 emissions data from 1998 to 2019 were input into the deep

111 learning model for training and validation. The frequency distribution of meteorological and emission data is

112 presented in Figure S1–S2 and discussed in Text S1. Before training the deep learning model, all meteorological and

emissions data were re-interpolated from their original spatial resolutions (meteorological data with 0.625° × 0.500°

114 and emission data with $0.5^{\circ} \times 0.5^{\circ}$) into the same grid as the surface PM_{2.5} data with a resolution of $0.1^{\circ} \times 0.1^{\circ}$. The

bilinear interpolation technique was applied in this work, which has been widely used to interpolate climate data into
 different resolutions in previous studies.^{39,40}

117 **2.2.** U-Net convolutional neural networks

118 Tremendous advances in computer vision have led to convolutional neural networks (CNNs) being widely used for 2D data analysis.⁴¹ We built a CNN-based U-Net framework to construct relationships between PM2.5 concentrations 119 and predictor variables.²¹ First proposed for medical segmentation,²¹ U-Net assumes that local information and global 120 121 information are both essential, which is also apposite for PM2.5 prediction. Equipped with flexible global aggregation 122 blocks, U-Net can sufficiently consider non-local influences from other grid cells to local PM2.5 concentration. In 123 addition, multiple layers of U-Net CNNs make it possible to elucidate nonlinear relationships among critical meteorological variables, ambient pollutant emissions, and surface PM2.5 concentrations; these relationships can be 124 too complex to be delineated through traditional regression methods. 42-44 125

Deleted: Covering the 1750–2100 period (historical dataset: 1750–2014, future emissions dataset: 2015–2100), the CMIP6 gridded emissions dataset has previously been used for assessing air control policies and for comparing divergent emissions scenarios.

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132 All of the predictor variables (meteorological and emission data) and the PM2.5 concentrations were treated as 2D 133 images. The detailed architecture of our U-Net model, including the number of channels for each convolution layer, 134 the size of the convolution kernel, the activation function of the convolution layer, and the image size are provided 135 in Figure 1. The description of the U-Net model can be found in Text S2, The data augmentation and dropout 136 regularization have been applied to improve the model generalization ability, as discussed in Text S3. And the 137

monotonic decreases in training and validation loss (Figure S4) have proved that no overfitting was detected.





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Figure 1. Architecture of the U-Net model

140 2.3. Future climate data under different Shared Socioeconomic Pathway (SSP) scenarios

141 The trained model was used to predict the 2021-2100 PM2.5 concentrations using the meteorological variables from 142 the CMIP6 future climate scenarios dataset. As shown in Table S4, historical simulations (1981-2010) and future 143 projections (2021-2100) of global climate multiple-model ensemble results from 28 global climate models (GCMs) 144 and four SSPs (SSP1-2.6, SSP2-4.5, SSP3-7.0, and SSP5-8.5) were utilized. The four SSPs are classified by 145 socioeconomic, land use, and environmental development assumptions and represent conceivable future scenarios 146 that capture distinctive climate mitigation and adaptation challenges. SSP1-2.6, SSP2-4.5, SSP3-7.0, and SSP5-8.5 147 represent low, medium, medium to high, and high radiative forcing by the end of the century, respectively.45-47 148 Changes in greenhouse gas concentrations in the atmosphere affect radiative forcing; thus, 'radiative forcing' 149 mentioned in this work corresponds to different greenhouse gas (GHG) emission scenarios and the resulting climate

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154 change. Both SSP1-2.6 and SSP5-8.5 represent strong climate mitigation scenarios, 17, 48 with the distinction that the 155 anthropogenic radiative forcings by 2100 are 2.6 Watt/m² and 8.5 Watt/m², respectively.^{20,49} SSP2-4.5 represents a moderate mitigation scenario and the radiative forcing is stabilized at 4.5 Watt/m² until 2100 by implementing 156 moderately restrictive emission reduction measures and strategies.¹⁸ SSP3-7.0 is the weakest climate mitigation 157 scenario with an anthropogenic radiative forcing of 7.0 Watt/m² by 2100.¹⁹ The critical elements relevant to air 158 pollution among four SSP scenarios are summarized in Table S5. Further information and the assumptions used in 159 160 the future scenarios are provided in Eyring et al. (2016)⁵⁰ and Gidden et al. (2019).⁵¹ The SSPs explored in this study cover a wide range of plausible socioeconomic trends for this century. 161

162 2.4. Bias correction and downscaling

Before being fed into the trained U-Net model, the meteorological variables from CMIP6 were corrected and downscaled to achieve reliable climate change impact metrics. To produce high-resolution and bias-corrected future climate information, we used the delta change (DC) method, which applies a change factor (i.e., delta) derived from GCMs to historical observations.^{52, 53} Studies have found the DC method to be robust for downscaling climate data.^{54, 55} Our implementation of the DC method was intended to correct the simulated climate data while providing results at high spatial resolution. The details of the DC method are described in the Text S4.

169 2.5. Mortality calculation

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170	The Global Exposure Mortality Model (GEMM) proposed by Burnett et al. (2018) ⁵⁶ was used as a hazard ratio model
171	to estimate the premature mortality burden associated with PM2.5 exposure (i.e., population-weighted PM2.5
172	concentration, Text S5). GEMM has relieved some of the contentious assumptions that are stipulated by other disease-
173	specific hazard ratio models, such as the Integrated Exposure Response Model. ⁵⁶ The detailed of the GEMM model
174	are provided in the Text S ₄
175	The baseline mortality rates for different countries in 2015 obtained from the Global Health Data Exchange data
175 176	The baseline mortality rates for different countries in 2015 obtained from the Global Health Data Exchange data catalog were used for estimating premature mortality. The gridded population projections for all SSPs during 2021–
175 176 177	The baseline mortality rates for different countries in 2015 obtained from the Global Health Data Exchange data catalog were used for estimating premature mortality. The gridded population projections for all SSPs during 2021–2100 at a resolution of 1 km \times 1 km are available from the Spatial Population Scenario database. This demographic
175 176 177 178	The baseline mortality rates for different countries in 2015 obtained from the Global Health Data Exchange data catalog were used for estimating premature mortality. The gridded population projections for all SSPs during 2021 –2100 at a resolution of 1 km × 1 km are available from the Spatial Population Scenario database. This demographic projection dataset has been previously verified ⁵⁷ and has been used to project heat-related excess mortality ^{58, 59} and

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to model future patterns of urbanization.⁶⁰ In this work, we calculated the PM_{2.5}-associated premature mortality in

accordance with the projected population, but the baseline mortality rate was assumed to be that of 2015 owing to a

184	future environmental burdens of disease ^{61, 62} .		
185	3. Results		
186	3.1. Performance evaluation		
187	To verify that the trained U-Net model could generate accurate PM _{2.5} concentration predictions, we validated the	*****	Deleted: well-
188	model performance from the spatial, scatter point, and statistical matrix perspectives. CMIP6 historical emissions		
189	data are available through 2014, while the data from 2015 to 2019 were from the CMIP6 future scenario emissions		
190	dataset. In the CMIP6 future scenario emissions dataset, the different scenarios (SSP1-2.6, SSP2-4.5, SSP3-7.0, and		
191	SSP5-8.5) have their own emissions datasets, but the differences are very limited throughout the 2015–2019 period.		
192	Because of this, we separated the verification by (1) implementing 8-fold cross-validation to verify the performance		
193	for the estimations from 1998 to 2014 and (2) inputting the future emissions datasets (2015-2019) of the four		
194	scenarios together with other independent variables into the trained model to output the PM2.5 estimation for the	*****	Deleted: well-
195	comparison. For the 8-fold cross-validation, 15 years of data were used for training and 2 years of data were used for		
196	comparison in each fold. The calculation of 8-fold cross-validation is further described in Text S7.		
197	Figure S5 shows a spatial comparison between the satellite-retrieved PM2.5 data and the values predicted by the U-		Deleted: 2
198	Net CNN using 8-fold validation. The results show that the model produced good fits in the areas with both low (\leq		<u></u>
199	<u>35 μg/m³) and high (> 35 μg/m³) PM_{2.5} concentration. As demonstrated in Figures S6 and S7, the errors between</u>		
200	the simulated and target monthly average $PM_{2.5}$ concentrations for all grid cells were within \pm 12 µg/m ³ for 1998-		
201	2014. The monthly average relative errors specific to each country were within $\pm 10\%$		Deleted: The results sho
202	Figure 2 shows the scatter plots of the satellite-retrieved PM _{2.5} concentrations and the 8-fold average predicted		the areas with both low (PM _{2.5} concentration. As
203	concentrations. The strong correlation coefficient (R, 0.987) was better than that of previous studies ⁶³⁻⁶⁵ and indicates		the error between the sin
204	that the model could accurately predict all of the 8-fold cross-validation data. The statistical evaluation metrics (A1-		annual relative errors spo
205	A6 in the supplemental material) shown in Table 1 were further used to verify the model performance. The relatively		± 10%.
206	small standard deviation of error indicates that our trained model has considerable stability. From these statistical	1	Deleted: A5
207	matrix perspectives, the $PM_{2.5}$ concentrations estimated by our proposed deep learning model were also better than		Deleted: The NMB, NM fold cross-validation we
208	those of previous studies. 29,66,67 In addition to the comparison with the satellite-retrieved $PM_{2.5}$ data, we compared		$0.2211 \pm 0.0274, -0.046$
209	the annual model-predicted $\text{PM}_{2.5}$ concentrations with the monitor-based observations in China, the United States,		$1.3622 \pm 0.1059 \mu\text{g/m}^3$

lack of credible alternatives. Constant baseline mortality has been applied in other works that have projected the

183

ow that the model gave a well-fitted in $(\leq 35\,\mu g/m^3)$ and high $(>35\,\mu g/m^3)$ demonstrated in Figures S3 and S4, mulated and target PM2.5 rid cells was within \pm 12 µg/m³. The becific to each country were within

E, MB, and MAGE of the average 8ere -0.0073 ± 0.0138 , $69\pm0.0848~\mu\text{g}/\text{m}^3,$ and , respectively.

- and Europe because these regions have well-established ground-based observation networks (Table SQ). The R values
- 226 for China, the United States, and Europe were 0.91, 0.80, and 0.81, respectively. These results show that the PM_{2.5}

227 estimates from our method were also in general agreement with the ground-based observations in these regions.

228



229 Figure 2. 8-fold cross-validation of the global PM2.5 concentrations predicted by the U-Net CNN model 230 during 1998-2014. The color represents the sample density. 231 Table 1. 8-fold cross-validation of U-Net CNN model performance MB³ MAGE RMSE NMB* NME* <u>R</u> $(\mu g/m^3)$ $(\mu g/m^3)$ $(\mu g/m^3)$ -0.01 <u>0.22</u> -0.05 1.36 4.02 0.987 Average Standard 0.01 0.03 0.08 0.11 0.39 0.010 error 232 *NMB: normalized mean bias; NME: normalized mean error; MB: mean bias; MAGE: mean absolute gross error; 233 RMSE: Root Mean Squared Error 235 As mentioned above, the CMIP6 emissions from 2015-2019 under the four SSP scenarios together with other input 236 data were fed into the trained deep learning model to estimate the PM2.5 concentrations for these 5 years, as shown in 237 Table S7, These metrics indicate the good feasibility and generalizability of our model in predicting the PM2.5 238 concentrations. In summary, the satisfactory performance indicated that the trained U-Net model was able to identify 239 the relationships between PM2.5 and the influencing factors, which demonstrates that this model could be used for 240 future PM2.5 pollution estimation in the 2021-2100 period under different climate scenarios.

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Deleted: 8-fold cross-validation of the PM_{2.5} concentrations predicted by the U-Net convolutional neural network model. The color represents the sample density.

Deleted: Table 1. 8-fold cross-validation of U-Net neural network model performance¶

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Deleted: The NMB ranged from 0.146 to 0.157 with an average of 0.148, the NME ranged from 0.338 to 0.341 with an average of 0.339, the MB ranged from 0.824 to 0.828 μ g/m³, and the MAGE ranged from 1.911 to 1.957 μ g/m³.

....[1]
258 **3.2.** Projection of future ambient PM_{2.5} concentrations

The built U-Net deep learning model was used to project future PM_{2.5} concentrations under the SSP1-2.6, SSP2-4.5, SSP3-7.0, and SSP5-8.5 scenarios. Changes in the downscaled multi-model ensembles of critical meteorological variables are shown in Figures S<u>8</u>-S12, Emissions (SO₂, NH₃, OC, BC, NOx) for the four SSP scenarios up to 2100 are shown in Figures S13-S17. The projected PM_{2.5} concentrations were compared with the baseline concentration (the average PM_{2.5} concentration from 2010 to 2019), as shown in Figure 3. The PM_{2.5} decadal average concentrations



Figure 3. Spatial distribution of changes in projected global PM_{2.5} concentrations relative to the baseline period (2010–2019) under different climate change scenarios. Panels (a)-(d) represent the changes in PM_{2.5} concentration for 2030s (2021-2050 average), 2050s (2041-2070 average), 2070s (2061-2090 average), and 2080s (2071-2100 average) under SSP1-2.6 scenarios compared to the baseline condition. Panels (e)-(h) represent that of the same period but under SSP2-4.5. Panels (i)-(l) represent that of the same period but under SSP3-7.0. Panels (m)-(p) represent that of the same period but under SSP5-8.5,

Based on the deep learning model estimations, the PM_{2.5} concentrations are projected to decrease in almost all regions*
in all scenarios; however, there are some notable differences among the projections. In SSP1-2.6, the projected PM_{2.5}
concentration will decrease consistently from 2030 to 2100. Among the investigated regions, the Middle East, Eastern

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284	China, and India will undergo the most significant decline in PM _{2.5} concentrations under this scenario. SSP2-4.5
285	represents the middle range of plausible future pathways. In this scenario, although the furthest projection into the
286	2090s showed a decline compared with the baseline level (that of the 2010s), this reduction was much smaller than
287	the corresponding changes under SSP1-2.6. The projections are different for SSP3-7.0, which assumes more
288	pessimistic development strategies, such as less investment in the environment and health care and a fast-growing
289	population. $^{17,\ 19,\ 68}$ This would lead to an apparent increase in $PM_{2.5}$ concentrations in Asia and Africa before the
290	2050s. After meeting economic development needs and implementing environmental control measures, the $PM_{2.5}$
291	concentrations would decrease to a level similar to the baseline period. In SSP5-8.5, fossil fuels are heavily relied on
292	to achieve rapid economic growth. Thus, in the middle of the 21st century, climate and emission change would
293	considerably increase PM2.5 concentrations and cause considerable damage to human health in central Africa.
294	Nevertheless, with the rapid development of society and pollution mitigation policies, the overall $PM_{2.5}$
295	concentrations will undergo a sharper reduction after the 2050s. PM2.5 concentrations continued to exceed baseline
296	values in central Africa under SSP3-7.0 and SSP5-8.5, which is quite consistent with the emission-increasing trends
297	in the region as shown in Figure S22 and S23, implying that the emission change should be the major driver for the
298	PM _{2.5} concentration increase in Central Africa.

299

3.3. Projection of future ambient PM_{2.5} exposure

SSPs narratives gave rise to spatial and temporal differences in the demographic projections. Figures S24 and S25
 show the demographic projections for the four SSPs scenarios for the world and for different regions, respectively.
 The projected population density (persons/km²) and the corresponding variations (compared to the situation in the
 2010s) in four SSP scenarios are shown in Figure S26. Combined with demographic projections, the exposure
 concentration can be estimated and used to assess the PM_{2.5} exposure associated health impacts.^{69, 70}

Figure 4 shows the projected $PM_{2.5}$ exposure concentrations in several representative regions (North America, South America, Europe, Africa, the Middle East, Russia and Economies in Transition [EIT], Asia, and the rest of the world) under the various SSP scenarios. The region boundaries are shown in Figure S27, Overall, $PM_{2.5}$ exposure is highest in the SSP3-7.0 scenario and lowest in the SSP1-2.6 scenario for the major representative regions of the world, although the main drivers for the projected outcomes differ. **Deleted:** Thus, in the middle of the 21^{st} century, climate change would considerably increase the PM_{2.5} concentrations and cause considerable damage to human health in central Africa.

Deleted: Derived from the disproportionate spatial and temporal asymmetry under four SSP scenarios, the PM_{2.5} exposure concentrations that coalesced with the future geographically demographic information can reveal the health intimidation to people from the future. Figures S14 and S15 show the demographic projections for the four SSPs scenarios for the world and for different regions, respectively.

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322 In Europe and North America, where PM2.5 concentrations will be relatively low, the population distribution is the 323 main determinant of PM2.5 exposure. Spatially-averaged PM2.5 concentrations will be lower in the SSP5-8.5 scenario 324 owing to the stronger pollution control measures than in the "middle of the road" SSP2-4.5 scenario, but the 325 population-weighted PM2.5 concentrations in SSP5-8.5 will slightly exceed those of SSP2-4.5 and even surpass those 326 of SSP3-7.0 after the 2060s. These trends will be caused by the higher birthrate in Europe and North America in SSP5-8.5 driven by economic optimism and international migration, leading to accelerated population growth in 327 328 these two regions (Figures S25 and S28).⁷¹ This implies that a greater share of the population will be concentrated in 329 areas with higher levels of social development and education. Therefore, compared with SSP2-4.5, the SSP5-8.5 scenario will result in a higher population-weighted PM2.5 exposure in North America and Europe after the 2060s. 330

331 In both Asia and Africa, PM2.5 exposure will decline steadily over time, reaching -58.2% (-47.3%) and -52.5% (-32.0%) for Asia (Africa) by the end of the century under the SSP1-2.6 and SSP5-8.5 scenarios, respectively, 332 compared with the baseline period. However, there will be no significant decline under the SSP3-7.0 scenario, and 333 334 before the 2060s, the exposure levels will be even higher than in the baseline period. Two explanations can be offered 335 for the persistently high exposure concentrations in Asia and Africa under the SSP3-7.0 scenario. The emissions and 336 unfavorable meteorological factors will lead to increased PM2.5 pollution under this scenario before the 2030s. 337 Meanwhile, population increase due to high fertility accompanied by slow urbanization in these regions will intensify 338 the density of urban and rural settlement patterns, thereby increasing PM_{2.5} exposure.⁷¹

339 The proportion of the population that would be exposed to the PM2.5 concentration below previous and current Air 340 Quality Guideline (AQG) values is also estimated under future climate change scenarios. As shown in Figure S29, 341 the differences between SSP1-2.6 scenario and the other three scenarios are considerable. Compared with the other 342 three scenarios, SSP1-2.6 would result in the largest fraction of the population exposed to the PM2.5 level that is lower 343 than 5 µg/m3. In the SSP1-2.6 scenario, 3.5% of the world's population will live in areas that have PM25 344 concentrations lower than 5 μ g/m³ by 2100, which is well above the baseline (2.0%). The other scenarios are 345 comparable in terms of the proportion of the population exposed to the PM2.5 concentration that is below the current 346 AQG values.

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Deleted: We also estimated the proportion of the population that would be exposed to the previous and current Air Quality Guideline (AQG) values under future climate change scenarios. As shown in Figure S18, the trends in the population fraction exposed to the AQG values of 10 $\mu\text{g/m}^3$ and 5 μ g/m³ are similar for the four climate change scenarios, although there are considerable differences in the magnitude of the population fraction that would be exposed. By 2100, in the SSP1-2.6 scenario, 3.5% of the world's population will live in areas that have PM2.5 concentrations lower than 5 µg/m3, which is well above the baseline population fraction of 2.0%. Compared with the other three scenarios, SSP1-2.6 would emerge victorious with tremendous benefits to global public health. Once SSP1-2.6 is not approachable, the other scenarios are comparable in terms of the proportion of the population exposed to the two AQG values.





Figure 4. Projected ambient PM_{2.5} exposure concentrations for 2030–2100 under different climate change scenarios.

370 **3.4. Projection of premature mortality burden**

371 The global premature mortality burden associated with future PM2.5 concentrations under the different SSP scenarios 372 was also analyzed. Figure 5 shows the PM2.5-associated premature deaths for the baseline (2010-2019) and future 373 (2030-2100) periods in several representative regions. The green growth and sustainable development assumptions 374 in the SSP1-2.6 scenario would lead to a rapid reduction in air pollution emissions globally. Therefore, the number 375 of PM2.5-associated premature deaths worldwide would start to decline in the near future (2031-2040) before the 376 population growth turning point (2071-2080). Given the middle-road development pattern of SSP2-4.5, premature 377 deaths in this scenario would peak at 9,024,000 (95% Confidence Interval (CI): 6,352,000-11,236,000) in the 2060s 378 and then steadily decline to 7,394,000 (95% CI: 5,202,000-9,291,000) in the final decade of the century, which is a 379 less rapid decline than in the SSP1-2.6 scenario. SSP3-7.0 assumes weak pollution control in which the 380 implementation of pollution mitigation measures is delayed and less ambitious in the long term. In this scenario, 381 premature deaths would spike dramatically in all regions except North America, Europe, and Russia and would not 382 decrease until the end of the century. The global number of PM2.5-associated premature deaths would reach 11,149,000 (95% CI: 7,877,000-13,800,000) in 2091-2100, an increase of 63% from the baseline period. In the 383 384 SSP5-8.5 scenario, which emphasizes technological progress and rapid economic growth through human capital 385 development, environmental issues become a priority health concern, and ambitious air quality goals result in 386 pollutant levels well below current levels in the medium to long term.^{16, 72} Therefore, in SSP5-8.5, global premature 387 deaths would peak at 8,509,000 (95% CI: 5,981,000–10,617,000) in the 2040s and then decline to 6,258,000 (95% 388 CI: 4,410,000-7,887,000, in the second half of the 21st century as high-performance pollution control technologies 389 are developed. This decrease would result in a smaller premature death burden than in the baseline period.

Deleted: 9,023,922 (95% CI: 6,352,113–11,236,028)

Deleted: 7,393,925 (95% CI: 5,202,070-9,290,539)

Deleted: 11,148,502 (95% CI: 7,876,580-13,800,471)

Deleted: 8,508,685 (95% CI: 5,980,955-10,617,435)

Deleted: 6,257,869 (95% CI: 4,410,176-7,886,851)



Deleted: Figure 5. PM_{2.5}-associated premature deaths (> 25 years old) in different regions. The red bars represent the premature mortality rate, and the vertical black lines indicate the 95% empirical confidence intervals.

Because the size of the population will determine the absolute number of premature deaths, country-specific mortality rates per 100,000 people were used to describe the $PM_{2.5}$ -associated mortality burden. Figure S3Q shows the mortality rate per 100,000 people for 184 countries or districts. Overall, countries in North America, Western Europe, and Oceania will have the lowest mortality rates. The mortality rates in Eastern European countries (e.g., Ukraine and Serbia) will be the highest, followed by some countries in Asia, such as China and India.

407 **3.5.** Key factors that influence the premature mortality burden

Two sensitivity studies were conducted to explore how future population distributions and $PM_{2.5}$ concentrations would affect the burden of $PM_{2.5}$ -associated premature mortality (Table S<u>8</u>). In the first sensitivity experiment (SA1), the only contributor to the difference in the estimated premature deaths from the baseline period is the demographic transition, while the contributor to the difference in the second sensitivity experiment (SA2) is the $PM_{2.5}$ variation,

412 When considering only the future demographic projections (i.e., demographic changes and changes in total 413 population by age), the changes in the population distribution over the coming decades (2021-2040) will exacerbate 414 the burden of premature deaths in all four scenarios, but the magnitude of the effect differs among the scenarios. 415 These differences are reflected in the demographic assumptions about the birthrate, mortality, and migration.⁷³ SSP1-416 2.6 and SSP5-8.5 both envision a development path of increased investment in education and health, thereby 417 accelerating the demographic transition.71 Therefore, in these two scenarios, the demographic turning point in 418 population decline will be reached earlier, in the medium term (2050s) (Figure S25), after which the impact of 419 demographics on the burden of premature mortality will gradually decrease.

420 In the second sensitivity experiment, we explore the effect of the PM2.5 concentration on premature mortality 421 assuming a constant future population distribution and size. Disease burden alleviation resulting from implementing 422 air pollution control measures will become apparent in the near future under the SSP1-2.6 and SSP5-8.5 scenarios. 423 SSP1-2.6 is the only scenario in which the effect of the PM2.5 concentration will be greater than the effect of 424 population size by the end of the century. Rapidly declining emissions would successfully offset the burden of 425 premature mortality resulting from population growth by the end of the century. Under the SSP3-7.0 scenario, the 426 planetary boundary layer height (PBLH) exerts strong influence on PM2.5 dispersion, and thus its decreases in East 427 Asia, South Asia, and eastern Africa (Figure S10) will increase the PM2.5 concentrations. Besides PBLH, other

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Deleted: In the first (SA1) and second (SA2) sensitivity experiment, the population size and the PM_{2.5} concentration was the same as that in 2010–2019, respectively.

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435 meteorological conditions, such as higher temperature,⁷⁴ are also favorable for PM_{2.5} accumulation in these regions

436 and therefore exacerbate the PM_{2.5}-associated mortality burden until the 2050s.

437

438 **3.6. Implications and limitations**

Global climate change is a significant challenge for society, and its impact on future air pollution is a critical perspective that requires quantitative assessment. Herein, a global $PM_{2.5}$ concentration dataset with a spatial resolution of $0.1^{\circ} \times 0.1^{\circ}$ was estimated based on SSP scenarios.

From the methodology and dataset perspectives, this work provides a new set of global-scale future PM_{2.5} dataset in 10km spatial resolution. This dataset can be used by others for air quality-related studies at the national and even regional scales. The dataset can be downloaded from the link listed in Text S8. The method developed in this work can also be implemented for other air pollution-related research. Researchers can further develop other more advanced deep learning frameworks for relevant studies based on the design of the method proposed in this work.

From the results perspective, this work has quantified how the future PM_{2.5} and its associated adverse health impacts will change based on different SSP scenarios. Based on our results, governments and relevant stakeholders from different countries can generally understand to what extent can PM_{2.5} influence their specific local health burdens. This can provide useful scientific references for future air pollution control policy design. In addition, when other studies come out in the future, the results from this work can also be used for the comparison. For example, compared to the adverse effects caused by other pollutants, such as O₃, which pollutant should the government put onto the priority position under different SSP scenarios.

454	From the health-economic impact perspective, the results of economic burdens shed light on the relationship between
455	mortality cost that is associated with PM2.5 pollution and economic development in various countries under different
456	future scenarios. The economic burdens related to future PM2.5 pollution are discussed in Text S9. Figure S31 and
457	Figure S32 show the economic loss that is associated with PM2.5-related health burdens. For most OECD countries,
458	China, and Central Asia, air pollution mitigation and economic development can have a beneficial synergistic effect.
459	The ratio of economic loss associated with PM2.5 pollution over the total GDP (PPP based) is minimal in the
460	sustainable development scenario (SSP1-2.6). For Central Africa and South America, from PM2.5 associated
461	economic loss perspective, these countries may consider choosing SSP2-4.5 pathway as their development modes.

Deleted: Under the SSP3-7.0 scenario, the planetary boundary layer height critically influences PM_{2.5} dispersion, and it decreases in East Asia, South Asia, and eastern Africa (Figure S7). The decrease in the planetary boundary layer height will increase the PM_{2.5} concentrations and therefore exacerbate the PM_{2.5}-associated mortality burden until the 2050s in these regions.

Deleted: The results showed that the global PM_{2.5} concentrations and the associated PM_{2.5} exposure and premature mortality burden vary considerably under the four SSP scenarios. Among the scenarios, SSP1-2.6 would have the earliest inflection point for PM_{2.5}-associated premature deaths and the lowest mortality burden. This scenario presents an ideal target pathway that governments should strive to achieve.

477 This work has some limitations. First, satellite-retrieved PM2.5 datasets were used as training targets, but according 478 to the results in Table S6 there were discrepancies with the observational data obtained from ground measurements. 479 Second, future climate, emission, and population projections harbor relatively large uncertainty, even if they have 480 been calibrated against observed patterns of changes using historical data.^{23, 71} Third, there are no generalizable and 481 accurate findings that indicate how baseline mortality rates will change in the future. Therefore, in accordance with previous studies^{75, 76} in the projection literature, we assumed that the nonlinear relationship between PM_{2.5} 482 concentrations and the baseline mortality rate would also be consistent. Fourth, the PM2.5 projections derived in this 483 study were based on several underlying assumptions. Primarily, in line with previous works,75,76 the relationships 484 485 between PM2.5 concentrations and meteorological conditions and precursor emissions explored in this study were 486 assumed to be true for future climate and emissions scenarios. Fifth, our predictions were based on the premise that 487 the world is steadily developing, and our method cannot predict the effects of uncontrollable factors (such as war and 488 strong earthquakes) on PM2.5 and population distributions. Finally, the biases in emissions data (e.g., bias in future 489 wildfires and missing windblown dust), can be directly propagated to the air pollution concentration estimation. Thus, 490 PM2.5 projections in this work contain unavoidable uncertainty. The spatial pattern of windblown dust was not 491 included in this study, which may have an influence on our results, especially for the Sahara and Middle East. Given 492 the proximity of these regions to large sources of dust emissions, there is a possibility that an underestimation of 493 PM2.5 concentrations would occur in these regions. However, the impact on the mortality estimations is limited since 494 these regions are more sparsely populated. Despite these limitations, this work helps quantify the extent to which 495 climate change will influence PM2.5 concentrations worldwide. The results can contribute to the ongoing assessment 496 of PM2.5-associated exposure and vulnerability under different climate change scenarios, and governments can use 497 this information to design useful strategies to reduce pollution.

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